## Provided for non-commercial research and educational use.

 Not for reproduction, distribution or commercial use.
## PLSKA <br> STUDIA MATHEMATICA BULGARICA

## ПЛИСКА

БЪЛГАРСКИ МАТЕМАТИЧЕСКИ СТУДИИ

The attached copy is furnished for non-commercial research and education use only. Authors are permitted to post this version of the article to their personal websites or institutional repositories and to share with other researchers in the form of electronic reprints.

Other uses, including reproduction and distribution, or selling or licensing copies, or posting to third party websites are prohibited.

For further information on
Pliska Studia Mathematica Bulgarica
visit the website of the journal http://www.math.bas.bg/~pliska/
or contact: Editorial Office
Pliska Studia Mathematica Bulgarica
Institute of Mathematics and Informatics
Bulgarian Academy of Sciences
Telephone: (+359-2)9792818, FAX:(+359-2)971-36-49
e-mail: pliska@math.bas.bg

# EXISTENCE THEOREMS FOR NON-COOPERATIVE ELLIPTIC SYSTEMS 

G. Boyadzhiev


#### Abstract

Existence of classical $C^{2}(\Omega) \bigcap C(\bar{\Omega})$ solutions of non-cooperative weakly coupled systems of elliptic second-order PDE is proved via the method of sub- and super-solutions.


1. Introduction. Let $\Omega \in R^{n}$ be a bounded domain with smooth boundary $\partial \Omega$. In this paper are considered weakly coupled linear elliptic systems of the form

$$
\begin{equation*}
L_{M} u=f(x) \text { in } \Omega \tag{1}
\end{equation*}
$$

and boundary data

$$
\begin{equation*}
u(x)=g(x) \text { on } \partial \Omega \tag{2}
\end{equation*}
$$

where $L_{M}=L+M, L$ is a matrix operator with null off-diagonal elements $L=\operatorname{diag}\left(L_{1}, L_{2}, \ldots, L_{N}\right)$, and matrix $M=\left\{m_{k i}(x)\right\}_{k, i=1}^{N}$. Scalar operators

$$
L_{k} u^{k}=-\sum_{i, j=1}^{n} D_{j}\left(a_{i j}^{k}(x) D_{i} u^{k}\right)+\sum_{i=1}^{n} b_{i}^{k}(x) D_{i} u^{k}+c^{k} u^{k} \text { in } \Omega
$$

are supposed uniformly elliptic ones for $k=1,2, \ldots, N$, i.e. there are constants $\lambda, \Lambda>0$ such that

$$
\lambda|\xi|^{2} \leq \sum_{i, j=1}^{n} a_{i j}^{k}(x) \xi_{i} \xi_{j} \leq \Lambda|\xi|^{2}
$$

Key words: Elliptic systems, non-cooperative, existence, sub- and super-solution.
for every $k$ and any $\xi=\left(\xi_{1}, \ldots, \xi_{n}\right) \in R^{n}$.
Right-hand side $f(x)$ is supposed a bounded vector-function, that is

$$
\begin{equation*}
\left|f^{l}(x)\right| \leq C \text { in } \Omega \tag{*}
\end{equation*}
$$

for every $l=1, \ldots, N$, where $C$ is a positive constant.
Coefficients $c^{k}$ and $m_{i k}$ in (1) are supposed continuous in $\bar{\Omega}$, and $a_{i j}^{k}(x)$, $b_{i}^{k}(x) \in C^{1}(\Omega) \cap C(\bar{\Omega})$. Assume in addition that for every $k=1, \ldots, N$

$$
\begin{equation*}
\left\{\sum_{i=1}^{n}\left(\sum_{j=1}^{n} D_{j} a_{i j}^{k}(x)+b_{i}^{k}(x)\right)^{2},\left|c^{k}\right|\right\} \leq b \tag{3}
\end{equation*}
$$

holds for $x \in \bar{\Omega}$, where $b$ is a positive constant.
Hereafter by $f^{-}(x)=\min (f(x), 0)$ and $f^{+}(x)=\max (f(x), 0)$ are denoted the non-negative and, respectively, the non-positive part of the function f . The same convention is valid for matrixes as well. For instance, we denote by $M^{+}$the non-negative part of $M$, i.e. $M^{+}=\left\{m_{i j}^{+}(x)\right\}_{i, j=1}^{N}$.

In this paper is employed the method of sub- and super-solutions in order to prove the existence of a classical $C^{2}(\Omega) \bigcap C(\bar{\Omega})$ solution of problem (1). A key-point of the method is the validity of the comparison principle. Unlike the cooperative systems, for non-cooperative ones there is no complete theory for the validity of the comparison principle. In [1] are given some sufficient conditions such that the comparison principle holds, which are recalled in section "Comparison principle for non-cooperative linear elliptic systems" below.

We consider linear systems only for the sake of simplicity. The results hold as well for quasi-linear weakly coupled elliptic systems

$$
\begin{aligned}
& Q^{l}(u)=-\operatorname{diva}^{l}\left(x, u^{l}, D u^{l}\right)+F^{l}\left(x, u^{1}, \ldots, u^{N}, D u^{l}\right)=f^{l}(x) \text { in } \Omega \\
& u^{l}(x)=g^{l}(x) \text { on } \partial \Omega
\end{aligned}
$$

for $l=1, \ldots, N$, where the coefficients $a^{l}(x, u, p), F^{l}(x, u, p), f^{l}(x), g^{l}(x)$ are supposed to be at least measurable functions with respect to the $x$ variable and locally Lipschitz continuous on $u$ and $p$.

## 2. Comparison principle for non-cooperative linear elliptic sys-

 tems. Let us recall the following Theorem (Theorem 3 in [1]):Theorem 1. Let (1) be a weakly coupled elliptic system with irreducible cooperative part of $L_{M^{-}}^{*}$. Then the comparison principle holds for the classical solutions of system (1) if there is $x_{0} \in \Omega$ such that

$$
\begin{equation*}
\lambda+\sum_{k=1}^{N} m_{k j}^{+}\left(x_{0}\right)>0 \text { for } j=1 \ldots, N \tag{4}
\end{equation*}
$$

and

$$
\begin{equation*}
\lambda+m_{j j}^{+}(x) \geq 0 \text { for every } x \in \Omega \text { and } j=1 \ldots, N \tag{5}
\end{equation*}
$$

where $\lambda$ is the principal eigenvalue of the operator $L_{M^{-}}$in $\Omega$.
The same result holds if the cooperative part of $L_{M^{-}}^{*}$ has structure with Jordan cells on the main diagonal and zeroes otherwise (Theorem 4 in [1]).

Theorem 2. Assume $m_{i j}^{-} \equiv 0$ for $i \neq j$ and (2) is satisfied. Then the comparison principle holds for the classical $C^{2}(\Omega) \bigcap C(\bar{\Omega})$ solutions of system (1) if there is $x_{0} \in \Omega$ such that

$$
\begin{equation*}
\lambda_{j}+\sum_{k=1}^{N} m_{k j}^{+}\left(x_{0}\right)>0 \text { for every } j=1 \ldots, N, \text { and } \tag{6}
\end{equation*}
$$

$$
\begin{equation*}
\lambda_{j}+m_{j j}^{+}(x) \geq 0 \text { for every } x \in \Omega \text { and } j=1 \ldots, N \tag{7}
\end{equation*}
$$

where $\lambda_{j}$ is the principal eigenvalue of $\widetilde{L}_{j}=L_{j}+m_{j j}^{-}$in $\Omega$.
Theorem 2 is formulated for diagonal matrix $M^{-}$, but the statement is valid with obvious modification if $M^{-}$has Jordan cells on the main diagonal.

Finally (Theorem 5 in [1]), in case that the cooperative part $M^{-}$is triangular, we have

Theorem 3. Assume the cooperative part $M^{-}$of system (1) is triangular, i.e. $m_{i j}^{-}=0$ for $i=1, \ldots, N, j>i$. Then the comparison principle holds for the classical $C^{2}(\Omega) \bigcap C(\bar{\Omega})$ solutions of system (1), if there is $\varepsilon>0$ such that

$$
\begin{equation*}
\lambda_{j}-\left(1-\delta_{1 j}\right) \varepsilon+\sum_{k=1}^{N} m_{k j}^{+}\left(x_{0}\right)>0 \tag{8}
\end{equation*}
$$

for $j=1 \ldots, N$ and some $x_{0} \in \Omega$ and
(9) $\quad \lambda_{j}-\left(1-\delta_{1 j}\right) \varepsilon+m_{j j}^{+}(x) \geq 0$ for every $x \in \Omega$ and $j=1 \ldots, N$,
where $\lambda_{j}$ is the principal eigenvalue of the operator $L_{j}+m_{j j}^{-}$.
3. Existence of classical solution. The first step of the method is existence of super- and sub-solution of system (1), (2). It is easy to check that constant-vector $(M, \ldots, M)$ is a super-solution for any constant $M$ such that

$$
\begin{equation*}
\sum_{i=1}^{n} m_{k i}(x) \geq \frac{C}{M} \tag{10}
\end{equation*}
$$

where $C$ is the upper bound $\left|f^{l}(x)\right|$ (see $\left.(*)\right)$.
Theorem 4. Suppose conditions (4), (5); (6), (7) or (8), (9) hold for system (1), (2), according to the structure of matrix $M$, as well as (10). Assume $v(x)$ is a classical super-solution and $w(x)$ is a a classical sub-solution of (1), (2). Then there exists a classical solution $u(x)$ of the problem (1), (2) with null boundary data.

Since the system (1) is a linear one, we assume in the following proof without loss of generality that $g(x)=0$.

Sketch of the proof. Let denote

$$
F^{k}\left(x, u^{1}, \ldots, u^{N}\right)=\sum_{i=1}^{n} m_{k i}(x) u^{i}+c^{k} u^{k}
$$

1. Consider the sequence of vector - functions $u_{0}, u_{1}, \ldots, u_{l}, \ldots$, where $u_{0}=$ $w(x)$ and $u_{l} \in H_{0}^{1}(\Omega)$ defines $u_{l+1}$ by induction as a solution of the problem

$$
\begin{align*}
-\sum_{i, j=1}^{N} D_{i}\left(a_{i j}^{k}(x) D_{j} u_{l+1}^{k}\right)+\sum_{i=1}^{N} & b_{i}^{k}(x) D u_{l+1}^{k}+\sigma u_{l+1}^{k}=  \tag{11}\\
& =f^{k}(x)-F^{k}\left(x, u_{k}^{1}, \ldots, u_{k}^{N}\right)+\sigma u_{l}^{k} \text { in } \Omega
\end{align*}
$$

with null boundary conditions

$$
\begin{equation*}
u_{l+1}^{k}(x)=0 \text { on } \partial \Omega \tag{12}
\end{equation*}
$$

for every $k=1, \ldots, N$.
Let denote the left-hand side of (11) by $A^{k}(x, u, \sigma)$, and the right-hand side - by $B^{k}(x, u, \sigma), k=1, \ldots, N$.

The problem (11), (12) is reducible system and in fact decomposes to $N$ independent equations. Then Theorem 8.3 in [3] (page 348) is applicable, hence these equations are solvable in $C^{2, \alpha}(\bar{\Omega})$ and

$$
\begin{equation*}
\left\|u_{l}^{k}\right\|_{C^{\beta}(\bar{\Omega})}<c \tag{13}
\end{equation*}
$$

$$
\begin{equation*}
\left\|\frac{\partial u_{l}^{k}}{\partial x_{i}}\right\|_{C^{\beta}(\bar{\Omega}}<c_{1} \text { for every } i=1, \ldots, n, \gamma=1, \ldots, m \tag{14}
\end{equation*}
$$

Furthermore $u_{0}^{l} \leq u_{1}^{l} \leq \cdots \leq u_{l+1}^{k} \leq \cdots$ by the comparison principle.
The proof of $u_{0}^{l} \leq u_{1}^{l}$ is trivial since $u_{0}^{l}$ is a sub-solution of (1), (2).
3. Obviously the inequality $u_{l+1}(x) \leq v(x)$ holds for every $u_{l+1}$, since $v(x)$ is a super-solution of the same system (1), (2).
4. The sequence of vector-functions $\left\{u^{k}\right\}$ is monotonously increasing and bounded from above in $\Omega$. Therefore there is a function $u$ such that $u^{k}(x) \rightarrow u(x)$ point-wise in $\Omega$. Furthermore, (13) yields $\left\{u^{k}\right\}$ is uniformly equicontinuous in $\bar{\Omega}$ and $\left\{u^{k}\right\}<$ const, since $u_{l}^{k}(x)$ is Holder continuous and therefore $\mid u_{l}^{k}(x)-$ $u_{l}^{k}\left(x_{0}\right) \mid \leq c\left(\left|x-x_{0}\right|^{\beta}\right)$ for every $l=1, \ldots, N$. By Arzela-Ascoli compactness criterion there is a sub-sequence $\left\{u_{k_{j}}\right\}$ that converges uniformly to $u \in C(\bar{\Omega})$. For convenience we denote $\left\{u_{k_{j}}\right\}$ by $\left\{u^{k}\right\}$.

Since $u \in C(\bar{\Omega})$ and all functions $\left\{u_{k_{j}}\right\}$ satisfy the null boundary conditions, then $u$ satisfies the boundary conditions as well.

The functions $u^{k}$ are Holder continuous with the same Holder constant, therefore $u$ is Holder continuous as well with the same Holder constant, i.e. $u \in C^{\beta}(\bar{\Omega})$.

Since $u_{l+1}(x)$ is monotone and $u(x)$ is continuous, then $\left\{\left(u^{k}\right)^{2}\right\} \rightarrow u^{2}$ in $\Omega$. Then the Dominated Convergence Theorem (Theorem 5 at p. 648 in [2]) yields $u^{k} \rightarrow u(x)$ in $\left(L^{2}(\Omega)\right)^{N}$.
5. Analogously to the previous step, (14) yields $\left\{D_{i} u^{k}\right\}$ is uniformly equicontinuous in $\bar{\Omega}$ and $\left\{D_{i} u^{k}\right\}<$ const. According to Arzela-Ascoli compactness criterion there is sub-sequence $\left\{D_{i} u_{k_{j}}\right\}$ that converges uniformly to $D_{i} u \in C(\bar{\Omega})$. For convenience we denote $\left\{u_{k_{j}}\right\}$ by $\left\{u^{k}\right\}$.

$$
\begin{aligned}
& \text { 6. For every } 0<\eta(x)=\left(\eta^{1}(x), \ldots, \eta^{N}(x)\right) \in\left(H_{0}^{1}(\Omega)\right)^{N} \\
& \begin{array}{r}
\int_{\Omega}\left(\sum_{i, j=1}^{N} a_{i j}^{k}(x) D_{j} u_{l+1}^{k} D_{i} \eta^{k}(x)+\sum_{i=1}^{N} b_{i}^{k}(x) D u_{l+1}^{k} \eta^{k}(x)+\sigma u_{l+1}^{k} \eta^{k}(x)\right) d x= \\
\\
=\int_{\Omega}\left(f^{k}(x)-F^{k}\left(x, u_{k}^{1}, \ldots, u_{k}^{N}\right)+\sigma u_{l}^{k}\right) \eta^{k}(x) d x
\end{array}
\end{aligned}
$$

holds and for $k \rightarrow \infty$ we obtain

$$
\begin{aligned}
& \int_{\Omega}\left(\sum_{i, j=1}^{N} a_{i j}^{k}(x) D_{j} u^{k} D_{i} \eta^{k}(x)+\sum_{i=1}^{N} b_{i}^{k}(x) D u^{k} \eta^{k}(x)\right) d x= \\
&=\int_{\Omega}\left(f^{k}(x)-F^{k}\left(x, u^{1}, \ldots, u^{N}\right)\right) \eta^{k}(x) d x
\end{aligned}
$$

that is $u(x)$ is solution of (1), (2).

## REFERENCES

[1] G. Boyadzhiev. Comparison principle for non-cooperative elliptic systems. Nonlinear Anal. 69, 11 (2008), 3838-3848.
[2] L. C. Evans. Partial Differential Equations. Graduate Studies in Mathematics, vol. 19. Providence, RI, AMS, 1998.
[3] O. A. Ladyzhenskaya, N. Ural'tseva. Linear and Quasilinear Equations of Eliptic Type. Moscow, Nauka, 1964 (in Russian).

Institute of Mathematics and Informatics
Bulgarian Academy of Sciences
Acad. G. Bonchev Str., Bl. 8
1113 Sofia, Bulgaria
e-mail: gpb@math.bas.bg

