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# EXISTENCE OF CLASSICAL SOLUTIONS OF QUASI-LINEAR NON-COOPERATIVE ELLIPTIC SYSTEMS 

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Method of sub- and super-solutions is applied in investigation of solvability in classical $C^{2}(\Omega) \bigcap C(\bar{\Omega})$ sense of quasi-linear non-cooperative weakly coupled systems of elliptic second-order PDE.

## 1. Introduction

In this paper is considered a major application of the comparison principle, namely the method of sub- and super-solutions, in order to derive some sufficient conditions for solvability in $C^{2}$ of a quasi-linear non-cooperative elliptic system.

Let $\Omega \in R^{n}$ be a bounded domain with smooth boundary $\partial \Omega$. In this paper are considered quasi-linear weakly-coupled elliptic systems of the type

$$
\begin{gather*}
Q^{l}(u)=-\operatorname{div} a^{l}\left(x, u^{l}, D u^{l}\right)+F^{l}\left(x, u^{1}, \ldots, u^{N}, D u^{l}\right)=f^{l}(x) \text { in } \Omega  \tag{1}\\
u^{l}(x)=g^{l}(x) \text { on } \partial \Omega \tag{2}
\end{gather*}
$$

for $l=1, \ldots, N$.

[^0]System (1) is strictly elliptic one, i.e. there are monotonously decreasing continuous function $\lambda(|u|)>0$ and monotonously increasing one $\Lambda(|u|)>0$, depending only on $|u|=\left(\left(u^{1}\right)^{2}+\cdots+\left(u^{N}\right)^{2}\right)^{1 / 2}$, such that

$$
\begin{equation*}
\lambda(|u|)\left|\xi^{l}\right|^{2} \leq \sum_{i, j=1}^{n} \frac{\partial a^{l i}}{\partial p_{j}^{l}}\left(x, u^{1}, \ldots, u^{N}, p^{l}\right) \xi_{i}^{l} \xi_{j}^{l} \leq \Lambda(|u|)\left|\xi^{l}\right|^{2} \tag{3}
\end{equation*}
$$

holds for every $u^{l}$ and $\xi^{l}=\left(\xi_{1}^{l}, \ldots, \xi_{n}^{l}\right) \in R^{n}, l=1,2, \ldots, N$.
Coefficients $a^{l}(x, u, p), F^{l}(x, u, p), f^{l}(x)$ and $g^{l}(x)$ are supposed at least measurable functions in $\Omega$ with respect to $x$ variable, and locally Liepshitz continuous with respect to $u^{l}, u$ and $p$, i.e.

$$
\left|F^{l}(x, u, p)-F^{l}(x, v, q)\right| \leq C(K)(|u-v|+|p-q|)
$$

$$
\begin{equation*}
\left|a^{l}\left(x, u^{l}, p\right)-a^{l}\left(x, v^{l}, q\right)\right| \leq C(K)\left(\left|u^{l}-v^{l}\right|+|p-q|\right) \tag{4}
\end{equation*}
$$

holds for every $x \in \Omega,|u|+|v|+|p|+|q| \leq K, l=1, \ldots, N$.
Furthermore we suppose $a^{l}(x, u, p)$ and $F^{l}(x, u, p)$ to be differentiable on $u^{l}$ and $p^{l}$, and

$$
\frac{\partial a^{l i}}{\partial p_{j}}, \frac{\partial a^{l i}}{\partial u^{k}}, \frac{\partial F^{l}}{\partial p_{l}}, \frac{\partial F^{l}}{\partial u^{k}} \in L^{1}(\Omega)
$$

Hereafter by $f^{-}(x)=\min (f(x), 0)$ and $f^{+}(x)=\max (f(x), 0)$ are denoted the non-negative and, respectively, the non-positive part of the function f . The same convention is valid for matrices as well. For instance, we denote by $M^{+}$the non-negative part of $M$, i.e. $M^{+}=\left\{m_{i j}^{+}(x)\right\}_{i, j=1}^{N}$.

## 2. Comparison principle for quasi-linear elliptic systems

 Let $u(x) \in\left(C^{2}(\Omega) \cap C(\bar{\Omega})\right)^{N}$ be classical sub-solution of (1), (2). Then$$
\int_{\Omega}\left(a^{l i}\left(x, u^{l}, D u^{l}\right) \eta_{x_{i}}^{l}+F^{l}\left(x, u^{1}, \ldots, u^{N}, D u^{l}\right) \eta^{l}-f^{l}(x) \eta^{l}\right) d x \leq 0
$$

for $l=1, \ldots, N$ and for every non-negative vector-function $\eta \in\left(W_{c}^{1}(\Omega) \cap C(\bar{\Omega})\right)^{N}$ (i.e. $\eta=\left(\eta^{1}, \ldots, \eta^{N}\right), \eta^{l} \geq 0, \eta^{l} \in W^{1, \infty}(\Omega) \cap C(\bar{\Omega})$ and $\eta^{l}=0$ on $\partial \Omega$ ).

Analogously, let $v(x) \in\left(C^{2}(\Omega) \cap C(\bar{\Omega})\right)^{N}$ be a classical super-solution of (1), (2). Then

$$
\int_{\Omega}\left(a^{l i}\left(x, v^{l}, D v^{l}\right) \eta_{x_{i}}^{l}+F^{l}\left(x, v^{1}, \ldots, v^{N}, D v^{l}\right) \eta^{l}-f^{l}(x) \eta^{l}\right) d x \geq 0
$$

for $l=1, \ldots, N$ and every non-negative vector-function $\eta \in\left(W_{c}^{1}(\Omega) \cap C(\bar{\Omega})\right)^{N}$.
Recall that the comparison principle holds for (1), (2), if $Q(u) \leq Q(v)$ in $\Omega$ and $u \leq v$ on $\partial \Omega$ yields $u \leq v$ in $\Omega$.

Since $u(x)$ and $v(x)$ are sub- and super-solutions, then $\widetilde{w}(x)=u(x)-v(x)$ is weak sub-solution of the following problem

$$
-\sum_{i, j=1}^{n} D_{i}\left(B_{j}^{l i} D_{j} \widetilde{w}^{l}+B_{0}^{l i} \widetilde{w}^{l}\right)+\sum_{k=1}^{N} E_{k}^{l} \widetilde{w}^{k}+\sum_{i=1}^{n} H_{i}^{l} D_{i} \widetilde{w}^{l}=0 \text { in } \Omega
$$

with non-positive boundary data on $\partial \Omega$, i.e.

$$
\int_{\Omega}\left(\sum_{i, j=1}^{n}\left(B_{j}^{l i} D_{j} \widetilde{w}^{l}+B_{0}^{l i} \widetilde{w}^{l}\right) \eta_{x_{i}}^{l}+\sum_{k=1}^{N} E_{k}^{l} \widetilde{w}^{k} \eta^{l}+\sum_{i=1}^{n} H_{i}^{l} D_{i} \widetilde{w}^{l} \eta^{l}\right) d x \leq 0 \text { in } \Omega
$$

Here

$$
\begin{aligned}
B_{j}^{l i} & =\int_{0}^{1} \frac{\partial a^{l i}}{\partial p_{j}}\left(x, P^{l}\right) d s, \quad B_{0}^{l i}=\int_{0}^{1} \frac{\partial a^{l i}}{\partial u^{l}}\left(x, P^{l}\right) d s \\
P^{l} & =\left(v^{l}+s\left(u^{l}-v^{l}\right), D v^{l}+s D\left(u^{l}-v^{l}\right)\right) \\
E_{k}^{l} & =\int_{0}^{1} \frac{\partial F^{l}}{\partial u^{k}}\left(x, S^{l}\right) d s, \quad H_{i}^{l}=\int_{0}^{1} \frac{\partial F^{l}}{\partial p_{i}}\left(x, S^{l}\right) d s \\
S^{l} & =\left(v+s(u-v), D v^{l}+s D\left(u^{l}-v^{l}\right)\right)
\end{aligned}
$$

Therefore $\widetilde{w}_{+}(x)=\max (\widetilde{w}(x), 0)$ is weak sub-solution of

$$
\begin{equation*}
-\sum_{i, j=1}^{n} D_{i}\left(B_{j}^{l i} D_{j} \widetilde{w}_{+}^{l}+B_{0}^{l i} \widetilde{w}_{+}^{l}\right)+\sum_{k=1}^{N} E_{k}^{l} \widetilde{w}_{+}^{k}+\sum_{i=1}^{n} H_{i}^{l} D_{i} \widetilde{w}_{+}^{l}=0 \text { in } \Omega \tag{5}
\end{equation*}
$$

with null boundary data on $\partial \Omega$.

Equation (5) is equivalent to

$$
\begin{equation*}
B_{E} \widetilde{w}_{+}=(B+E) \widetilde{w}_{+}=0 \text { in } \Omega \tag{6}
\end{equation*}
$$

where $B=\operatorname{diag}\left(B_{1}, B_{2}, \ldots, B_{N}\right), B_{l}=-\sum_{i, j=1}^{n} D_{i}\left(B_{j}^{l i} D_{j} \widetilde{w}_{+}^{l}+B_{0}^{l i} \widetilde{w}_{+}^{l}\right)+\sum_{i=1}^{n} H_{i}^{l} D_{i} \widetilde{w}_{+}^{l}$ and $E=\left\{E_{k}^{l}\right\}_{l, k+1}^{N}$.

Then the following theorem (Theorem (8) in [1]) holds:

Theorem 1. Let (1), (2) be quasi-linear system and corresponding system $B_{E^{-}}$in (6) is elliptic one. Then comparison principle holds for system (1), (2) if $B_{E^{-}}$is irreducible one and for every $j=1, \ldots, n$ hold
(i) $\quad \lambda+\left(\sum_{k=1}^{N} \frac{\partial F^{k}}{\partial p^{j}}\left(x, p, q^{l}\right)+\sum_{i=1}^{N} D_{i} \frac{\partial a^{j i}}{\partial p^{j}}\left(x, p^{j}, q^{j}\right)\right)^{+}>0$ for some $x_{0} \in \Omega$,

$$
\begin{equation*}
\lambda+\left(\sum_{i=1}^{n} D_{i} \frac{\partial a^{j i}}{\partial p^{j}}\left(x, p^{j}, q^{j}\right)+\frac{\partial F^{j}}{\partial p^{j}}\left(x, p, q^{j}\right)\right)^{+} \geq 0 \quad \text { for every } x \in \Omega \tag{ii}
\end{equation*}
$$

where $p, q \in R^{n}$ and $\lambda$ is the first eigenvalue of operator $B_{E^{-}}$in $\Omega$; or if $B_{E^{-}}$is reducible one and for every $j=1, \ldots, n$ hold
(i') $\quad \lambda_{j}+\left(\sum_{k=1}^{N} \frac{\partial F^{k}}{\partial p^{j}}\left(x, p, q^{j}\right)+\sum_{i=1}^{N} D_{i} \frac{\partial a^{j i}}{\partial p^{j}}\left(x, p^{j}, q^{j}\right)\right)^{+}>0$ for some $x_{0} \in \Omega$,
$\left(i i^{\prime}\right) \quad \lambda_{j}+\left(\sum_{i=1}^{n} D_{i} \frac{\partial a^{j i}}{\partial p^{j}}\left(x, p^{j}, q^{j}\right)+\frac{\partial F^{j}}{\partial p^{j}}\left(x, p, q^{j}\right)\right)^{+} \geq 0 \quad$ for every $x \in \Omega$,
where $p, q \in R^{n}$ and $\lambda_{l}$ is the first eigenvalue of operator $B_{l}$ in $\Omega$.

Note: We remind the reader that $B_{E-}$ stands for the negative part of $B_{E}$. Irreducible matrix is one that can not be decomposed to matrices of lower rank, and respectively, the reducible matrix can be decomposed.

## 3. Existence of classical solutions

In order to use the method of sub- and super-solutions we need some constraints on the growth of the coefficients. Assume that for every $l=1, \ldots, N$

$$
\begin{equation*}
\left\{\sum_{i=1}^{n}\left(\sum_{j=1}^{n} D_{j} B_{j}^{l i}+\left(B_{0}^{l i}+H_{i}^{l}\right)\right)^{2},\left|\sum_{i=1}^{n}\left(D_{i} B_{0}^{l i}\right)\right|\right\} \leq b \tag{7}
\end{equation*}
$$

holds for $x \in \bar{\Omega}$, where $b$ is a positive constant,

$$
\begin{equation*}
\left[\sum_{i=1}^{n}\left(B_{0}^{l i}+H_{i}^{l}\right) \cdot p_{i} \cdot u^{l}+\sum_{i=1}^{n}\left(D_{i} B_{0}^{l i}\right) u^{l}+\sum_{k=1}^{n} E_{k}^{l} \cdot u_{k}(x)\right] u^{l} \geq c_{1}|u|^{2}-c_{2} \tag{8}
\end{equation*}
$$

for every $x \in \Omega, l=1, \ldots, N$ and arbitrary vectors $u$ and $p$, where $c_{1}=$ const $>0$ and $c_{2}=$ const $\geq 0$,

$$
\begin{gather*}
\left|\sum_{i=1}^{n}\left(B_{0}^{l i}+H_{i}^{l}\right) \cdot p_{i} \cdot u^{l}+\sum_{i=1}^{n}\left(D_{i} B_{0}^{l i}\right) u^{l}+\sum_{k=1}^{n} E_{k}^{l} \cdot u_{k}(x)\right| \leq  \tag{9}\\
\leq \varepsilon\left(C_{M}\right)+P\left(p, C_{M}\right)\left(1+|p|^{2}\right)
\end{gather*}
$$

where $P\left(p, C_{M}\right) \rightarrow 0$ for $|p| \rightarrow \infty$ and $\varepsilon\left(C_{M}\right)$ is sufficiently small and depends only on $n, N, C_{M}, \lambda$ and $\Lambda$. $\lambda$ and $\Lambda$ are the constants from condition (3) and

$$
\begin{equation*}
C_{M}=\max \left\{\max _{\partial \Omega}|u|, \frac{2 \max |f(x)|}{c_{1} n}, \sqrt{\frac{2 c_{2}}{c_{1} n}}\right\} . \tag{10}
\end{equation*}
$$

Then the following theorem holds
Theorem 2. Suppose system (1), (2) satisfies conditions (3) to (9), and (i), (ii) or $\left(i^{\prime}\right)$, ( $\left.i i^{\prime}\right)$, according to the structure of matrix $E=\left(E_{k}^{l}\right)$. Assume that $v(x)$ is a classical super-solution and $w(x)$ is a a classical sub-solution of (1), (2). Then there exists a classical $C^{2}(\Omega) \bigcap C(\bar{\Omega})$ solution $u(x)$ of the problem (1), (2) with null boundary data.

Theorem 2 is proved by the method of sub- and super-solutions. A key-point of the method is the validity of the comparison principle. Unlike the cooperative systems, for non-cooperative ones there is no complete theory for the validity of the comparison principle. In [1] are given some sufficient conditions such that the comparison principle holds, which are recalled in section "Comparison principle for non-cooperative linear elliptic systems" below.

Since the system (1) is a quasi-linear one, we assume in the following proof without loss of generality that $g(x)=0$.

Proof of Theorem 2. Let us denote

$$
\Phi_{l}^{-}\left(x, u^{1}, \ldots, u^{N}\right)=\sum_{k=1}^{n} E_{k}^{l-} u^{k}+\sum_{i=1}^{n}\left(D_{i} B_{0}^{l i}\right) u^{l}
$$

and

$$
\Phi_{l}^{+}\left(x, u^{1}, \ldots, u^{N}\right)=\sum_{k=1}^{n} E_{k}^{l+} u^{k} .
$$

1. Consider the sequence of vector-functions $u_{0}, u_{1}, \ldots, u_{k}, \ldots$, where $u_{0}=$ $v(x)$ and $u_{k} \in H_{0}^{1}(\Omega)$ defines $u_{k+1}$ by induction as a solution of the problem (11)

$$
\begin{gathered}
-\sum_{i, j=1}^{n} D_{i}\left(B_{j}^{l i} D_{j} u_{k+1}^{l}+B_{0}^{l i} u_{k+1}^{l}\right)+\sum_{i=1}^{n} H_{i}^{l} D_{i} u_{k+1}^{l}+\Phi_{l}^{-}\left(x, u_{k+1}^{1}, \ldots, u_{k+1}^{N}\right)+\sigma u_{k+1}^{l}= \\
=f^{l}(x)-\Phi_{l}^{+}\left(x, u_{k}^{1}, \ldots, u_{k}^{N}\right)+\sigma u_{k}^{l} \text { in } \Omega
\end{gathered}
$$

with null boundary conditions

$$
\begin{equation*}
u_{k+1}^{l}(x)=0 \text { on partial } \Omega \tag{12}
\end{equation*}
$$

for every $l=1, \ldots, N, \sigma<0$ is a constant.
Let us denote the left-hand side of (11) by $A^{k}(x, u, \sigma)$, and the right-hand side - by $B^{k}(x, u, \sigma), k=1, \ldots, N$.

The problem (11), (12) is cooperative system and by Theorem (1) in [2], page 161, it is solvable. Even more, for the solution $u_{k+1}^{l}(x) \in C^{2}(\bar{\Omega})$ there is constant $\beta \in(0,1), \beta$ depends on $(l+1)$, such that

$$
\begin{equation*}
\left\|u_{k+1}^{l}\right\|_{C^{\beta}(\bar{\Omega})}<c, \tag{13}
\end{equation*}
$$

$$
\begin{equation*}
\left\|\frac{\partial u_{k+1}^{l}}{\partial x_{i}}\right\|_{C^{\beta}(\bar{\Omega})}<c_{1} \text { for every } i=1, \ldots, n \text { and } \gamma=1, \ldots, m . \tag{14}
\end{equation*}
$$

$$
\begin{equation*}
\text { For every compact set } K \subset \Omega \text { holds }\left\|\frac{\partial^{2} u_{k+1}^{l}}{\partial x_{i} \partial x_{j}}\right\|_{C^{\beta}(K)}<c_{7}(\rho) \tag{15}
\end{equation*}
$$

for every $i, j=1, \ldots, n, \rho=\operatorname{dist}(K, \partial \Omega)$, and the constants $c_{4}-c_{7}$ are independent on $k$. By Theorem 1 in [4] conditions (3)-(10) are necessary for solvability of
the corresponding PDEs, while by Theorem 4 in [4, p. 120], conditions (13)-(15) are derived in every subset of the domain where the coefficients of the diffraction problem are smooth. In our case this is the whole domain $\Omega$.

Furthermore $u_{0}^{l} \geq u_{1}^{l} \geq \cdots \geq u_{k+1}^{l} \geq \cdots$ by the comparison principle and the fact that

$$
\begin{gathered}
f^{l}(x)-\Phi_{l}^{+}\left(x, u_{k}^{1}, \ldots, u_{k}^{N}\right)+\sigma u_{k}^{l}-f^{l}(x)+\Phi_{l}^{+}\left(x, u_{k-1}^{1}, \ldots, u_{k-1}^{N}\right)-\sigma u_{k-1}^{l}= \\
=-\Phi_{l}^{+}\left(x, u_{k}^{1}-u_{k-1}^{1}, \ldots, u_{k}^{N}-u_{k-1}^{N}\right)+\sigma\left(u_{k}^{l}-u_{k-1}^{l}\right) \geq 0
\end{gathered}
$$

since $u_{l}^{k} \leq u_{l-1}^{N}$ and $-m_{k i}^{+}(x) \leq 0$
The proof of $u_{0}^{l} \geq u_{1}^{l}$ is trivial since $u_{0}^{l}$ is a super-solution of (1), (2).
3. Obviously the inequality $u_{k+1}(x) \geq w(x)$ holds for every $k$, since $w(x)$ is a sub-solution of the same system (1), (2).
4. The sequence of vector-functions $\left\{u_{k}\right\}$ is monotonously decreasing and bounded from below in $\Omega$. Therefore there is a function $u$ such that $u_{k}(x) \rightarrow u(x)$ point-wise in $\Omega$. Furthermore, (13) yields $\left\{u_{k}\right\}$ is uniformly equicontinuous in $\bar{\Omega}$ and $\left\{u_{k}\right\}<$ const, since $u_{k}^{l}(x)$ is Holder continuous and therefore $\mid u_{k}^{l}(x)-$ $u_{k}^{l}\left(x_{0}\right) \mid \leq c\left(\left|x-x_{0}\right|^{\beta}\right)$ for every $l=1, \ldots, N$. By Arzela - Ascoli compactness criterion there is a sub-sequence $\left\{u_{k_{j}}\right\}$ that converges uniformly to $u \in C(\bar{\Omega})$. For convenience we denote $\left\{u_{k_{j}}\right\}$ by $\left\{u_{k}\right\}$.

Since $u \in C(\bar{\Omega})$ and all functions $\left\{u_{k_{j}}\right\}$ satisfy the null boundary conditions, then $u$ satisfies the boundary conditions as well.

The functions $u_{k}$ are Holder continuous with the same Holder constant, therefore $u$ is Holder continuous as well with the same Holder constant, i.e. $u \in C^{\beta}(\bar{\Omega})$.

Since $u_{k+1}(x)$ is monotone and $u(x)$ is continuous, then $\left\{\left(u^{k}\right)^{2}\right\} \rightarrow u^{2}$ in $\Omega$. Then the Dominated Convergence Theorem (Theorem 5 at p. 648 in [3]) yields $u^{k} \rightarrow u(x)$ in $\left(L^{2}(\Omega)\right)^{N}$.
5. Analogously to the previous step, (14) yields $\left\{D_{i} u_{k}\right\}$ is uniformly equicontinuous in $\bar{\Omega}$ and $\left\{D_{i} u_{k}\right\}<$ const. According to Arzela-Ascoli compactness criterion there is sub-sequence $\left\{D_{i} u_{k_{j}}\right\}$ that converges uniformly to $D_{i} u \in C(\bar{\Omega})$. For convenience we denote again $\left\{u_{k_{j}}\right\}$ by $\left\{u_{k}\right\}$.
6. For every $0<\eta(x)=\left(\eta^{1}(x), \ldots, \eta^{N}(x)\right) \in\left(H_{0}^{1}(\Omega)\right)^{N}$

$$
\begin{gathered}
\int_{\Omega}\left(\sum_{i, j=1}^{n}\left(B_{j}^{l i} D_{j} u_{k+1}^{l}+B_{0}^{l i} u_{k+1}^{l}\right) D_{i} \eta^{l}(x)+\sum_{i=1}^{n} H_{i}^{l} D_{i} u_{k+1}^{l} \eta^{l}(x)\right) d x+ \\
+\int_{\Omega}\left(\Phi_{l}^{-}\left(x, u_{k+1}^{1}, \ldots, u_{k+1}^{N}\right)+\sigma u_{k+1}^{l}\right) \eta^{l}(x) d x=
\end{gathered}
$$

$$
=\int_{\Omega}\left(f^{l}(x)-\Phi_{l}^{+}\left(x, u_{k}^{1}, \ldots, u_{k}^{N}\right)+\sigma u_{k}^{l}\right) \eta^{l}(x) d x
$$

holds and for $k \rightarrow \infty$ we obtain

$$
\begin{aligned}
\int_{\Omega}\left(\sum_{i, j=1}^{n}\right. & \left.\left(B_{j}^{l i} D_{j} u^{l}+B_{0}^{l i} u^{l}\right) D_{i} \eta^{l}(x)+\sum_{i=1}^{n} H_{i}^{l} D_{i} u^{l} \eta^{l}(x)\right) d x+ \\
& +\int_{\Omega}\left(\Phi_{l}^{-}\left(x, u^{1}, \ldots, u^{N}\right)+\sigma u^{l}\right) \eta^{l}(x) d x= \\
= & \int_{\Omega}\left(f^{l}(x)-\Phi_{l}^{+}\left(x, u^{1}, \ldots, u^{N}\right)+\sigma u^{l}\right) \eta^{l}(x) d x
\end{aligned}
$$

that is $u(x)$ is solution of (1), (2).
7. Since the coefficients $a_{i j}^{k}(x)$ of the principal symbol in (1) are $C^{1+\alpha}(\Omega)$ smooth and $D_{x}^{2} u_{k}(x)$ are locally bounded, then $D_{x}^{2} u(x) \in C(\Omega)$.

In fact by the exhaustion of $\Omega$ by compact sets $\kappa_{r}, \kappa_{r} \subset \kappa_{r+1} \subset \Omega$ and $\bigcup \kappa_{r}=\Omega$, and by (15) we have $D_{x}^{2} u_{k} \in C^{\beta}\left(K_{r}\right)$ are uniformly bounded and equicontinuous in $\kappa_{r}$. Applying Arzela-Ascoli theorem and Cantor diagonal process (for sub-sequence and compact) yields $C^{2}$ smoothness in $\Omega$ of the limit function $u(x)$.

Therefore $\left.u(x) \in C^{2}(\Omega)\right)^{N}$ is classical solution of (1), (2).

## 4. Model example

Consider the system

$$
\left\lvert\, \begin{align*}
& \left(K^{2}-\chi^{2}\right)^{1 / 4} \Delta_{2} \ln |\chi-K|=2(2 K-\chi)  \tag{16}\\
& \left(K^{2}-\chi^{2}\right)^{1 / 4} \Delta_{2} \ln |\chi+K|=2(2 K+\chi)
\end{align*}\right.
$$

where $\Delta_{2}=\partial_{x}^{2}+\partial_{y}^{2}, K^{2}>\chi^{2}, K<0, K=K(x, y)$ and $\chi=\chi(x, y)$. Here $K$ is the Gaussian curvature and $\chi$ is the curvature of the normal connection on minimal non-super-conformal surface $M^{2}$ in $R^{4}$.

Every couple of solutions ( $K, \chi$ ) define uniquely minimal non-super-conformal surface $M^{2}$ in $R^{4}$ with Gaussian curvature $K$ and normal curvature $\chi$.

Let $K>\chi$. Then we denote

$$
\begin{align*}
& K-\chi=e^{u}  \tag{17}\\
& K+\chi=e^{v}
\end{align*}
$$

and transform (16) to

$$
\left\lvert\, \begin{align*}
& \Delta u=3 e^{(3 u-v) / 4}+e^{(3 v-u) / 4}  \tag{18}\\
& \Delta v=e^{(3 u-v) / 4}+3 e^{(3 v-u) / 4}
\end{align*} .\right.
$$

Equation (18) is quasi-linear non-cooperative elliptic system. In this case

$$
\begin{aligned}
B_{j}^{l i} & =\int_{0}^{1} \frac{\partial a^{l i}}{\partial p_{j}}\left(x, P^{l}\right) d s=\delta_{i, j}, \quad B_{0}^{l i}=\int_{0}^{1} \frac{\partial a^{l i}}{\partial u^{l}}\left(x, P^{l}\right) d s=0 \\
E_{1}^{1} & =\int_{0}^{1} \frac{\partial F^{1}}{\partial u^{1}}\left(x, S^{l}\right) d s=\int_{0}^{1} \frac{9}{4} e^{(3 u-v) / 4}-\frac{1}{4} e^{(3 v-u) / 4} d s \\
E_{2}^{1} & =\int_{0}^{1} \frac{\partial F^{1}}{\partial u^{2}}\left(x, S^{l}\right) d s=\int_{0}^{1}-\frac{3}{4} 3 e^{(3 u-v) / 4}+\frac{3}{4} e^{(3 v-u) / 4} d s \\
E_{1}^{2} & =\int_{0}^{1} \frac{\partial F^{2}}{\partial u^{1}}\left(x, S^{l}\right) d s=\int_{0}^{1} \frac{3}{4} e^{(3 u-v) / 4}-\frac{3}{4} e^{(3 v-u) / 4} d s \\
E_{2}^{2} & =\int_{0}^{1} \frac{\partial F^{2}}{\partial u^{2}}\left(x, S^{l}\right) d s=\int_{0}^{1}-\frac{1}{4} e^{(3 u-v) / 4}+\frac{9}{4} e^{(3 v-u) / 4} d s \\
H_{i}^{l} & =\int_{0}^{1} \frac{\partial F^{l}}{\partial p_{i}}\left(x, S^{l}\right) d s=0
\end{aligned}
$$

where $\delta_{i, j}$ is Kronecker delta (symbol), $P^{l}=\left(v^{l}+s\left(u^{l}-v^{l}\right), D v^{l}+s D\left(u^{l}-v^{l}\right)\right)$ and $S^{l}=\left(v+s(u-v), D v^{l}+s D\left(u^{l}-v^{l}\right)\right)$.

Since $K$ is the Gaussian curvature and $\chi$ is the curvature of the normal connection on minimal non-super-conformal surface $M^{2}$ in $R^{4}$, by (17) we presume $u, v$ do not blow up. In other words we suppose there is constant $C(\Omega)$ such that $e^{u} \leq C(\Omega)$ and $e^{v} \leq C(\Omega)$.

Assume that $\Omega$ is a map from $M^{2} \rightarrow M^{2}$. The smaller is the map, the smaller is $C(\Omega)$ and the larger is the first eigenvalue of system (11). Therefore, if $\Omega$ is sufficiently small, conditions $(i)$, (ii) (or $\left(i^{\prime}\right),\left(i^{\prime \prime}\right)$ ) hold and by Theorem 1 comparison principle holds for system (18). Furthermore, conditions (7)-(9) hold as well. This way we have constructed (locally) a classical solution of system (16) having intreresting applications in differential geometry. Details of the proofs of the results in this short note will be published elsewhere.

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[^0]:    2010 Mathematics Subject Classification: 35J47, 35J57.
    Key words: Elliptic systems, non-cooperative system, existence, sub- and super-solution.

