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AH₃-MANIFOLDS OF CONSTANT ANTIHOLOMORPHIC SECTIONAL CURVATURE

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The purpose of this paper is to prove that an AH₃-manifold of constant antiholomorphic sectional curvature is a real space form or a complex space form.

1. Introduction. Let M be a $2m$ -dimensional almost Hermitian manifold with metric tensor g and almost complex structure J . The Riemannian connection and the curvature tensor are denoted by ∇ and R , respectively.

If $\nabla J=0$ or $(\nabla_X J)X=0$, or

$$g((\nabla_X J)Y, Z) + g((\nabla_Y J)Z, X) + g((\nabla_Z J)X, Y) = 0,$$

then M is said to be a Kähler, or nearly Kähler, or almost Kähler manifold, respectively. The corresponding classes of manifolds are denoted by K , NK , AK . The general class of all almost Hermitian manifolds is denoted by AH . If L is a class of almost Hermitian manifolds, its subclass of L_I -manifolds is defined by the identity i), where

- 1) $R(X, Y, Z, U) = R(X, Y, JZ, JU)$;
- 2) $R(X, Y, Z, U) = R(X, Y, JZ, JU) + R(X, JY, Z, JU) + R(JX, Y, Z, JU)$;
- 3) $R(X, Y, Z, U) = R(JX, JY, JZ, JU)$.

It is well known, that

$$K = K_1 \subset NK = NK_2, \quad K \subset AK_2,$$

$$K = NK \cap AK, \quad AH_1 \subset AH_2 \subset AH_3,$$

see e. g. [4].

A plane α in $T_p(M)$ is said to be holomorphic (resp. antiholomorphic) if $\alpha = J\alpha$ (resp. $\alpha \perp J\alpha$). The manifold M is said to be of pointwise constant holomorphic (resp. antiholomorphic) sectional curvature ν , if for each point $p \in M$ the curvature of an arbitrary holomorphic (resp. antiholomorphic) plane α in $T_p(M)$ doesn't depend on α : $K(\alpha) = \nu(p)$.

For Kähler manifolds the requirements for constant holomorphic and constant antiholomorphic sectional curvature are equivalent [2]. In [3] is proved a classification theorem for nearly Kähler manifolds of constant holomorphic sectional curvature.

If M is a $2m$ -dimensional AH₃-manifold of pointwise constant antiholomorphic sectional curvature ν , and if $m > 2$, then ν is a global constant [5]. In [1] is proved a classification theorem for nearly Kähler manifolds of constant antiholomorphic sectional curvature and a corresponding result for AK₃-manifolds is obtained in [6].

In section 3 we shall prove the following theorem:

Theorem. *Let M be a $2m$ -dimensional AH₃-manifold, $m > 2$. If M is of pointwise constant antiholomorphic sectional curvature, then M is a real space form or a complex space form.*

Here a real space form means a Riemannian manifold of constant sectional curvature and a complex space form means a Kähler manifold of constant holomorphic sectional curvature.

2. Basic formulas. If M is an AH_3 -manifold, its Ricci tensor S satisfies

$$S(X, Y) = S(Y, X) = S(JX, JY).$$

If moreover M has pointwise constant antiholomorphic sectional curvature ν , its curvature tensor has the form

$$(2.1) \quad R = \frac{1}{6} \psi(S) + \nu \pi_1 - \frac{2m-1}{3} \nu \pi_2,$$

where

$$\begin{aligned} \psi(Q)(x, y, z, u) = & g(x, Ju)Q(y, Jz) - g(x, Jz)Q(y, Ju) - 2g(x, Jy)Q(z, Ju) \\ & + g(y, Jz)Q(x, Ju) - g(y, Ju)Q(x, Jz) - 2g(z, Ju)Q(x, Jy) \end{aligned}$$

for an arbitrary tensor Q of type $(0, 2)$ and

$$\pi_1(x, y, z, u) = g(x, u)g(y, z) - g(x, z)g(y, u),$$

$$\pi_2 = \frac{1}{2} \psi(g),$$

see [1]. According to (2.1), M is an AH_2 -manifold.

On the other hand, it is known, that if M is an AK_g -manifold,

$$(2.2) \quad R(x, y, z, u) - R(x, y, Jz, Ju) = \frac{1}{2} g((\nabla_x J)y - (\nabla_y J)x, (\nabla_z J)u - (\nabla_u J)z)$$

holds good [4].

We shall use also the second Bianchi identity

$$(2.3) \quad (\nabla_x R)(y, z, u, v) + (\nabla_y R)(z, x, u, v) + (\nabla_z R)(x, y, u, v) = 0.$$

3. Proof of the theorem

Lemma. *The conditions of the theorem imply that M is an Einsteinian manifold.*

Proof of Lemma. Let p be an arbitrary point of M and let $x, y \in T_p(M)$. According to the second Bianchi identity,

$$(3.1) \quad (\nabla_x R)(Jx, y, y, Jx) + (\nabla_{Jx} R)(y, x, y, Jx) + (\nabla_y R)(x, Jx, y, Jx) = 0.$$

Let $\{e_i, Je_i; i=1, \dots, m\}$ be an orthonormal basis of $T_p(M)$, such that $Se_i = \lambda_i e_i, i=1, \dots, m$. Putting in (3.1) $x=e_i, y=e_j$ or $x=e_k, y=e_i+e_j$ for $i \neq j \neq k \neq i$ and using (2.1), we obtain

$$(3.2) \quad (\nabla_{e_j} S)(e_i, e_j) + \{\lambda_i + \lambda_j - 2(2m-1)\nu\} g(Je_i, (\nabla_{e_j} J)e_j) = 0;$$

$$(3.3) \quad \begin{aligned} & (\nabla_{e_i} S)(e_j, e_k) + \{\lambda_i + \lambda_k - 2(2m-1)\nu\} g(Je_k, (\nabla_{e_j} J)e_i) \\ & + (\nabla_{e_j} S)(e_i, e_k) + \{\lambda_j + \lambda_k - 2(2m-1)\nu\} g(Je_k, (\nabla_{e_i} J)e_j) = 0, \end{aligned}$$

respectively. Analogously from

$$(\nabla_{e_j} R)(Je_j, e_j, e_j, Je_k) + (\nabla_{Je_j} R)(e_j, e_i, e_j, Je_k) + (\nabla_{e_j} R)(e_i, Je_j, e_j, Je_k) = 0$$

we find

$$(3.4) \quad \begin{aligned} & 3(\nabla_{e_i} S)(e_j, e_k) + 6\{\lambda_j - (2m-1)v\}g((\nabla_{e_j} R)e_j, Je_k) \\ & - (\nabla_{e_j} S)(e_i, e_k) - \{\lambda_i + \lambda_j - 2(2m-1)v\}g((\nabla_{e_j} J)e_i, Je_k) = 0 \end{aligned}$$

and hence

$$(3.5) \quad \begin{aligned} & 8(\nabla_{e_i} S)(e_j, e_k) + \{17\lambda_j - \lambda_i - 16(2m-1)v\}g((\nabla_{e_j} J)e_j, Je_k) \\ & + 3(\lambda_i - \lambda_j)g((\nabla_{e_j} J)e_i, Je_k) = 0. \end{aligned}$$

In (3.5) we change j and k and add the result with (3.5)

$$(3.6) \quad \begin{aligned} & 16(\nabla_{e_i} S)(e_j, e_k) + 17(\lambda_j - \lambda_k)g((\nabla_{e_j} J)e_j, Je_k) \\ & + 3(\lambda_i - \lambda_j)g((\nabla_{e_j} J)e_i, Je_k) + 3(\lambda_i - \lambda_k)g((\nabla_{e_k} J)e_i, Je_j) = 0. \end{aligned}$$

On the other hand, (3.3) and (3.4) imply

$$(3.7) \quad (3\lambda_j - \lambda_i - 2\lambda_k)g((\nabla_{e_i} J)e_j, Je_k) + (3\lambda_i - \lambda_j - 2\lambda_k)g((\nabla_{e_j} J)e_i, Je_k) = 0.$$

Hence it is not difficult to find

$$3(\lambda_j - \lambda_k)g((\nabla_{e_i} J)e_j, Je_k) + (\lambda_i - \lambda_j)g((\nabla_{e_j} J)e_i, Je_k) + (\lambda_i - \lambda_k)g((\nabla_{e_k} J)e_i, Je_j) = 0$$

and by using (3.6) this implies

$$(3.8) \quad 2(\nabla_{e_i} S)(e_j, e_k) = (\lambda_k - \lambda_j)g((\nabla_{e_i} J)e_j, Je_k).$$

Let us first assume that $g((\nabla_{e_i} J)e_j, Je_k) \neq 0$. Using three times (3.7), we obtain

$$\begin{aligned} & (3\lambda_i - \lambda_k - 2\lambda_j)(3\lambda_j - \lambda_i - 2\lambda_k)(3\lambda_k - \lambda_j - 2\lambda_i) \\ & - (3\lambda_i - \lambda_j - 2\lambda_k)(3\lambda_j - \lambda_k - 2\lambda_i)(3\lambda_k - \lambda_i - 2\lambda_j) = 0 \end{aligned}$$

or equivalently

$$(\lambda_i - \lambda_j)(\lambda_j - \lambda_k)(\lambda_k - \lambda_i) = 0.$$

Hence it follows $\lambda_i = \lambda_j = \lambda_k$. Indeed we have to consider two cases:

Case 1. $\lambda_i = \lambda_j$. In (3.7) we made a cyclic change of i, j, k and use $\lambda_i = \lambda_j$:

$$(3.9) \quad \begin{aligned} & (\lambda_i - \lambda_k)\{3g((\nabla_{e_j} J)e_k, Je_i) + g((\nabla_{e_k} J)e_i, Je_j)\} = 0, \\ & (\lambda_i - \lambda_k)\{g((\nabla_{e_k} J)e_i, Je_j) + 3g((\nabla_{e_i} J)e_j, Je_k)\} = 0. \end{aligned}$$

If $g((\nabla_{e_k} J)e_i, Je_j) = 0$ the last equation implies $\lambda_i = \lambda_k$, i. e. $\lambda_i = \lambda_j = \lambda_k$. So we assume $g((\nabla_{e_k} J)e_i, Je_j) \neq 0$. In (3.5) we change i and k and we use $\lambda_i = \lambda_j$ and (3.8)

$$\{17\lambda_i - \lambda_k - 16(2m-1)v\}g((\nabla_{e_k} J)e_j, Je_i) + 3(\lambda_k - \lambda_i)g((\nabla_{e_j} J)e_k, Je_i) = 0.$$

Hence, using (3.9), we obtain $\lambda_i = (2m-1)v$. On the other hand, (3.5) and (3.8) result

$$3\lambda_i + \lambda_k - 4(2m-1)v = 0$$

and so we find $\lambda_k = (2m-1)v$, i. e. $\lambda_i = \lambda_j = \lambda_k$.

Case 2. $\lambda_j = \lambda_k$. From (3.7) we obtain

$$(\lambda_i - \lambda_j)\{g((\nabla_{e_i} J)e_j, Je_k) - 3g((\nabla_{e_j} J)e_i, Je_k)\} = 0.$$

If $g((\nabla_{e_j} J)e_i, Je_k) = 0$ this implies $\lambda_i = \lambda_j$, so $\lambda_i = \lambda_j = \lambda_k$. But $g((\nabla_{e_j} J)e_i, Je_k) \neq 0$ is the Case 1.

So we have $\lambda_i = \lambda_j = \lambda_k$ and using (3.5) and (3.8), we find $\lambda_i = (2m - 1)v$. If $m = 3$ M is Einsteinian in p . Let $m > 3$. For $s \neq i, j, k$ we have

$$(\nabla_{e_i} R)(e_s, Je_s, e_j, Je_k) + (\nabla_{e_s} R)(Je_s, e_i, e_j, Je_k) + (\nabla_{Je_s} R)(e_i, e_s, e_j, Je_k) = 0.$$

Because of (2.1) this implies

$$(\nabla_{e_i} S)(e_j, e_k) + \{\lambda_j + \lambda_s - 2(2m - 1)v\}g((\nabla_{e_i} J)e_j, Je_k) = 0.$$

Hence, using $\lambda_j = \lambda_k = (2m - 1)v$ and (3.8), we derive $\lambda_s = (2m - 1)v$. Consequently M is Einsteinian in p .

Now we assume that

$$g((\nabla_x J)y, z) = 0$$

whenever x, y, z are chosen among the basic vectors $e_i, Je_i; i = 1, \dots, m$ and $x \neq y, z, Jy, Jz$. In (2.3) we put $x = Je_i, y = v = e_j, z = -Ju = e_k$ for $i \neq j \neq k \neq i$. Using (2.1), we obtain

$$(\nabla_{e_i} S)(e_i, e_j) + \{\lambda_j + \lambda_k - 2(2m - 1)v\}g(Je_i, (\nabla_{e_j} J)e_i) = 0.$$

From this equality and (3.2) it follows that if $g(Je_i, (\nabla_{e_j} J)e_i) \neq 0$ for some i, j , then $\lambda_s = \lambda_k$ for $s, k \neq j$. Consequently if $(\nabla_{e_s} J)e_s \neq 0$ for any $s \neq j$ then M is Einsteinian in p .

Let us assume that M is not Einsteinian in p . Then M is not Einsteinian in a neighbourhood U of p . We shall prove that M is an AK_3 -manifold in U . Let $q \in U$. If M is a Kähler manifold in q , M is almost Kähler in q . Let M is not Kähler in q . Let $f_i, Jf_i, i = 1, \dots, m$, be an orthonormal basis of $T_q(M)$, such that $Sf_i = \mu_i f_i, i = 1, \dots, m$. Since M is non Kähler and non Einsteinian in q we may assume that $(\nabla_{f_1} J)f_1 \neq 0, \mu_2 = \dots = \mu_m = \mu$ and

$$(3.10) \quad (\nabla_x J)y = 0, \quad g((\nabla_{f_1} J)x, y) = 0$$

whenever x, y are chosen among f_i, Jf_i for $i > 1$. Analogously to (3.2)

$$(3.2') \quad (\nabla_{f_j} S)(f_i, f_j) + \{\mu_i + \mu_j - 2(2m - 1)v\}g(Jf_i, (\nabla_{f_j} J)f_j) = 0$$

holds good and according to (3.10) this implies

$$(3.11) \quad (\nabla_{f_i} S)(f_i, f_j) = (\nabla_{Jf_j} S)(f_i, Jf_j) = 0 \text{ for } j > 1, j \neq i.$$

In (2.3) we put $x = f_i, y = -Jv = f_j, z = -Ju = f_1$ for $i \neq j \neq 1 \neq i$ and using (2.1), (3.10) and (3.11) we obtain

$$(3.12) \quad (\nabla_{f_i} S)(f_j, f_j) + (\nabla_{f_i} S)(f_1, f_1) - (\nabla_{f_1} S)(f_i, f_i) + 2\{\mu - (2m - 1)v\}g(Jf_i, (\nabla_{f_1} J)f_1) = 0.$$

Now let $k \neq i$. From

$$(\nabla_{f_i} R)(f_k, Jf_k, Jf_k, f_k) + (\nabla_{f_k} R)(Jf_k, f_i, Jf_k, f_k) + (\nabla_{Jf_k} R)(f_i, f_k, Jf_k, f_k) = 0$$

it follows

$$2(\nabla_{f_i} S)(f_k, f_k) - (\nabla_{f_k} S)(f_i, f_k) + \{\mu_i + \mu_k - 2(2m-1)v\}g(Jf_i, (\nabla_{f_k} J)f_k) \\ - (\nabla_{Jf_k} S)(f_i, Jf_k) + \{\mu_i + \mu_k - 2(2m-1)v\}g(Jf_i, (\nabla_{Jf_k} J)Jf_k) = 0.$$

Hence using (3.2'), we derive

$$(3.13) \quad (\nabla_{f_i} S)(f_k, f_k) = (\nabla_{f_k} S)(f_i, f_k) + (\nabla_{Jf_k} S)(f_i, Jf_k).$$

Now (3.11) and (3.13) imply

$$(\nabla_{f_i} S)(f_j, f_j) = 0 \quad \text{for } i, j > 1, i \neq j.$$

Then (3.12) takes the form

$$(\nabla_{f_i} S)(f_1, f_1) - (\nabla_{f_1} S)(f_i, f_1) + 2\{\mu - (2m-1)v\}g(Jf_i, (\nabla_{f_1} J)f_1) = 0$$

and using (3.13), we obtain

$$(\nabla_{Jf_1} S)(f_i, Jf_1) + 2\{\mu - (2m-1)v\}g(Jf_i, (\nabla_{f_1} J)f_1) = 0$$

which implies

$$(3.14) \quad (\nabla_{f_1} S)(f_i, f_1) + (\nabla_{Jf_1} S)(f_i, Jf_1) + 2\{\mu - (2m-1)v\}g(Jf_i, (\nabla_{f_1} J)f_1) + (\nabla_{Jf_1} J)Jf_1 = 0.$$

Since M is non Einsteinian in q the first equation of (3.2) and (3.14) result

$$(3.15) \quad (\nabla_{f_1} J)f_1 + (\nabla_{Jf_1} J)Jf_1 = 0.$$

From (3.10) and (3.15) it follows easily that M is an almost Kähler manifold in q . Consequently it is an almost Kähler manifold in U and hence an AK_g -manifold in U . If M is a Kähler manifold in U it is of constant holomorphic sectional curvature [2] and hence Einsteinian in U which contradicts our assumption. Let M is non Kähler in q (we shall use the above notations for the basis of $T_q(M)$) and let

$$(\nabla_{f_1} J)f_i = \alpha_i f_1 + \beta_i Jf_1 \quad \text{for } i > 1.$$

In (2.2) we put $x = u = f_i$, $y = z = f_1$:

$$v - \frac{1}{6}(\mu + \mu_1) + \frac{2m-1}{3}v = -\frac{1}{2}(\alpha_i^2 + \beta_i^2)$$

for $i > 1$ which implies

$$(3.16) \quad \alpha_i^2 + \beta_i^2 = \alpha_j^2 + \beta_j^2 \quad \text{for } i, j > 1.$$

Now we put in (2.2) ($x = f_i$, $y = z = f_1$, $u = f_j$), ($x = f_i$, $y = z = f_j$, $u = Jf_j$) respectively and we obtain

$$(3.17) \quad \alpha_i \alpha_j + \beta_i \beta_j = 0,$$

$$\alpha_i \beta_j - \alpha_j \beta_i = 0,$$

respectively. But (3.16) and (3.17) imply $\alpha_i = \beta_i = 0$ for $i > 1$ which is a contradiction. This proves Lemma.

Now we prove the theorem. Since M is Einsteinian (2.1) takes the form

$$R = \nu\pi_1 + \lambda\pi_2$$

with a constant λ . Consequently M is a real space form or a complex space form [7].

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Received 15. VIII. 1983