

ON AFFINE CONNECTIONS IN A RIEMANNIAN MANIFOLD WITH A CIRCULANT METRIC AND TWO CIRCULANT AFFINOR STRUCTURES*

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In the present paper it is considered a class V of 3-dimensional Riemannian manifolds M with a metric g and two affinor tensors q and S . It is defined another metric \bar{g} in M . The local coordinates of all these tensors are circulant matrices. It is found: 1) a relation between curvature tensors R and \bar{R} of g and \bar{g} , respectively; 2) an identity of the curvature tensor R of g in the case when the curvature tensor \bar{R} vanishes; 3) a relation between the sectional curvature of a 2-section of the type $\{x, qx\}$ and the scalar curvature of M .

1. Introduction. In this paper we investigate the class V of manifolds admitting an additional structure q , such that it's cube degree is the identity. In the basic manifold M the metric g is positively defined and q is a parallel structure with respect to the affine connection ∇ of g . By g and q we construct another metric f which is non-degenerate. By f we obtain an affine connection $\bar{\nabla}$. Our main problem is to find a subclass of V , such that $\bar{\nabla}$ is a locally flat connection.

We consider a 3-dimensional Riemannian manifold M with a metric tensor g and two affinor tensors q and S such that: their local coordinates form circulant matrices. So these matrices are as follows:

$$(1) \quad g_{ij} = \begin{pmatrix} A & B & B \\ B & A & B \\ B & B & A \end{pmatrix}, \quad A > B > 0,$$

where A and B are smooth functions of a point $p(x^1, x^2, x^3)$ on some $F \subset R^3$,

$$(2) \quad q_i^j = \begin{pmatrix} 0 & 1 & 0 \\ 0 & 0 & 1 \\ 1 & 0 & 0 \end{pmatrix}, \quad S_i^j = \begin{pmatrix} -1 & 1 & 1 \\ 1 & -1 & 1 \\ 1 & 1 & -1 \end{pmatrix}.$$

Let ∇ be the connection of g . The following results have been obtained in [1]:

$$(3) \quad q^3 = E; \quad g(qx, qy) = g(x, y), \quad x, y \in \chi M.$$

$$(4) \quad \nabla q = 0 \quad \Leftrightarrow \quad \text{grad } A = \text{grad } B.S.$$

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$$(5) \quad 0 < B < A \Rightarrow g \text{ is positively defined.}$$

If M has a metric g from (1), affiner structures q and S from (2) and $\nabla q = 0$, then we note for brevity that M is in the class V .

Now, we give an example of a manifold of this class. Let

$$(6) \quad A = (x^1)^2 + (x^2)^2 + (x^3)^2, \quad B = x^1x^2 + x^2x^3 + x^1x^3,$$

be two functions of a point $p(x^1, x^2, x^3) \neq (x, x, x)$. Then, $A > B > 0$ and

$$(7) \quad g_{ij} = \begin{pmatrix} A & B & B \\ B & A & B \\ B & B & A \end{pmatrix}$$

is positively defined. Also, we obtain $\text{grad } A = \text{grad } B \cdot S$ which implies $\nabla q = 0$. So, the manifold M with a metric g , defined by (6) and (7), and affiner structures q and S , defined by (2), is in the class V .

We denote $\tilde{q}_j^s = q_a^s q_j^a$, $\Phi_j^s = q_j^s + \tilde{q}_j^s$, and from (2) we have:

$$(8) \quad \tilde{q}_j^s = \begin{pmatrix} 0 & 0 & 1 \\ 1 & 0 & 0 \\ 0 & 1 & 0 \end{pmatrix}, \quad \Phi_j^s = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 0 & 1 \\ 1 & 1 & 0 \end{pmatrix}.$$

2. Affine connections. Let M be in V . We denote $f_{ij} = g_{ik}q_j^k + g_{jk}q_i^k$, i.e.

$$(9) \quad f_{ij} = \begin{pmatrix} 2B & A+B & A+B \\ A+B & 2B & A+B \\ A+B & A+B & 2B \end{pmatrix}.$$

We calculate $\det f_{ij} = 2(A-B)^2(A+2B) \neq 0$, so f is a non-degenerated symmetric tensor field. Evidently, we have that $\nabla q = 0$, which thank's to (2), (8) and (9), implies:

$$(10) \quad \nabla \tilde{q} = 0, \quad \nabla f = 0, \quad \nabla S = 0, \quad \nabla \Phi = 0.$$

For later use, from (1) – (9), we find next identities:

$$(11) \quad \Phi_j^s g_{is} = f_{ji}, \quad \Phi_j^s f_{is} = 2g_{ji} + f_{ji}, \quad f_{ji}g^{is} = \Phi_j^s, \quad g_{ji}f^{is} = \frac{1}{2}S_j^s.$$

Further, we suppose that α and β are two smooth functions in F , such that $\alpha \neq \beta$, $\alpha + 2\beta \neq 0$. Now, we construct the metric \bar{g} as follows

$$(12) \quad \bar{g} = \alpha \cdot g + \beta \cdot f.$$

The local coordinates of \bar{g} are

$$\bar{g}_{ij} = \begin{pmatrix} \alpha A + 2\beta B & \beta A + (\alpha + \beta)B & \beta A + (\alpha + \beta)B \\ \beta A + (\alpha + \beta)B & \alpha A + 2\beta B & \beta A + (\alpha + \beta)B \\ \beta A + (\alpha + \beta)B & \beta A + (\alpha + \beta)B & \alpha A + 2\beta B \end{pmatrix}.$$

Since $\det \bar{g}_{ij} = (\alpha - \beta)^2(A - B)^2(A + 2B)(\alpha + 2\beta) \neq 0$, \bar{g} is a non-degenerated tensor field.

Let $\alpha > \beta > 0$, then $\alpha A + 2\beta B > \beta A + (\alpha + \beta)B > 0$. Analogously to (5) we state that \bar{g} is positively defined.

Let $\alpha = 0, \beta \neq 0$.

(a) If $\beta > 0$, then the main minors of the matrix \bar{g}_{ij} are: $2\beta B > 0$, $\beta^2(B - A)(A + 3B) < 0$, $(-\beta)^2(A - B)^2(A + 2B)2\beta > 0$. We state that \bar{g} is an indefinite metric.

(b) If $\beta < 0$, then analogously to (a) we state that \bar{g} is an indefinite metric.

In [2] it is proved the next assertion:

Theorem 2.1. *Let M be a manifold in V , g and \bar{g} be two metrics of M , related by (12). Let ∇ and $\bar{\nabla}$ be the corresponding connections of g and \bar{g} . Then, $\bar{\nabla}q = 0$ if and only if, when*

$$(13) \quad \text{grad } \alpha = \text{grad } \beta \cdot S.$$

Let $\beta = 0$ in (12). Then, we have

$$(14) \quad \bar{g} = \alpha \cdot g.$$

The condition (14) defines the well-known conformal transformation in the Riemannian manifold M .

The general case, when $\alpha \neq 0$, $\beta \neq 0$ in (12), leads to very complex calculations and it will be an object of next investigations.

Now, we consider the case $\alpha = 0$ in (12). We obtain

$$(15) \quad \bar{g}_{ij} = \beta \cdot f_{ij}.$$

Then, from (13) we can get that $\bar{\nabla}q = 0$ if and only if, when β is a constant. Further, we suppose $\bar{\nabla}q \neq 0$, i.e. β is not a constant. Thanks to (15) we get

$$(16) \quad \nabla_k \bar{g}_{ij} = \beta_k f_{ij}, \quad \beta_k = \nabla_k \beta.$$

We have the well-known identities:

$$(17) \quad \bar{\nabla}_k \bar{g}_{ij} = \partial_k \bar{g}_{ij} - \bar{\Gamma}_{ki}^a \bar{g}_{aj} - \bar{\Gamma}_{kj}^a \bar{g}_{ai},$$

$$(18) \quad \nabla_k \bar{g}_{ij} = \partial_k \bar{g}_{ij} - \Gamma_{ki}^a \bar{g}_{aj} - \Gamma_{kj}^a \bar{g}_{ai},$$

$$(19) \quad \bar{\nabla}_k \bar{g}_{ij} = 0.$$

Using (11), (16) – (19), for the tensor $T_{ik}^s = \bar{\Gamma}_{ki}^s - \Gamma_{ki}^s$ of the affine deformation of ∇ and $\bar{\nabla}$ we find

$$(20) \quad T_{ik}^s = \beta_k \delta_i^s + \beta_i \delta_k^s - \frac{1}{2} \beta^a S_a^s f_{ik}, \quad \beta_k \sim \frac{\beta_i}{2\beta}.$$

We have that $\bar{\nabla}_i q_j^k = \nabla_i q_j^k - \beta_j q_i^k + \tilde{\beta}_j \delta_i^k - \frac{1}{2} \beta^a S_a^k q_j^t f_{ti} + \frac{1}{2} \beta^a S_a^t q_t^k f_{ij}$.

Let R be the curvature tensor field of ∇ . Let \bar{R} be the curvature tensor field of $\bar{\nabla}$. It is well-known the relation (see [3])

$$(21) \quad \bar{R}_{ijk}^h = R_{ijk}^h + \nabla_j T_{ik}^h - \nabla_k T_{ij}^h + T_{ik}^s T_{sj}^h - T_{ij}^s T_{sk}^h.$$

From (20) and (21) after some calculations we obtain

$$(22) \quad \begin{aligned} \bar{R}_{ijk}^h &= R_{ijk}^h + \delta_k^h (\nabla_j \beta_i - \beta_i \beta_j + \varphi f_{ij}) - \delta_j^h (\nabla_k \beta_i - \beta_i \beta_k + \varphi f_{ik}) \\ &+ \frac{1}{2} f_{ij} S_t^h (\nabla_k \beta^t - \beta_k \beta^t) - \frac{1}{2} f_{ik} S_t^h (\nabla_j \beta^t - \beta_j \beta^t), \quad \varphi = \frac{1}{2} \beta^t \beta_s S_t^s. \end{aligned}$$

Theorem 2.2. *Let M be in V , ∇ and $\bar{\nabla}$ be the Riemannian connections of g and \bar{g} , related by (15). If $\bar{\nabla}$ is a locally flat connection, then the curvature tensor field R of ∇*

is

$$(23) \quad \begin{aligned} R(x, y, z, u) = & \frac{\tau}{6} [(2g(x, u)g(y, z) - 2g(x, z)g(y, u) \\ & + (g(qx, u) + g(x, qu))(g(qy, z) + g(y, qz)) \\ & - (g(qx, z) + g(x, qz))(g(qy, u) + g(y, qu))], \end{aligned}$$

where $x, y, z, u \in \chi M$.

Proof. We have $\bar{R} = 0$. From (22) we find

$$(24) \quad R_{ijk}^h = \delta_j^h P_{ki} - \delta_k^h P_{ij} - f_{ij} Q_k^h + f_{ik} Q_j^h,$$

where $P_{ki} = \nabla_k \beta_i - \beta_i \beta_k + \varphi f_{ik}$, $Q_k^h = \frac{1}{2} S_t^h (\nabla_k \beta^t - \beta_k \beta^t)$.

Now, we put $k = h$ in (24) and with the help of (11) we get

$$(25) \quad R_{ij} = -P_{ij} - \psi f_{ij}, \quad \psi = \frac{1}{2} S_t^h \nabla_h \beta^t.$$

We note that $R_{ij} = R_{ijk}^k$ are the local coordinates of the Ricci tensor of ∇ , also $\tau = R_{ij} g^{ij}$ and $\tau^* = R_{ij} f^{ij}$ are the first and the second scalar curvatures of M , respectively. The identity (25) implies

$$(26) \quad \tau^* = -2\varphi - 4\psi.$$

Using (11), we have that $Q_k^h = P_{ka} f^{ah} - \varphi \delta_k^h$, and from (25) we get

$$(27) \quad Q_k^h = -R_{ka} f^{ah} - (\psi + \varphi) \delta_k^h.$$

We substitute (25) – (27) in (24), and find

$$(28) \quad R_{ijk}^h = \delta_k^h \left(R_{ij} - \frac{\tau^*}{2} f_{ij} \right) - \delta_j^h \left(R_{ki} - \frac{\tau^*}{2} f_{ki} \right) + f_{ij} R_{ka} f^{ah} - f_{ik} R_{ja} f^{ah}.$$

From (28) and $R_k^h = R_{ijk}^h g^{ij}$ we have

$$(29) \quad 2R_k^h = \tau \delta_k^h + \frac{\tau^*}{2} \Phi_k^h - \Phi_k^t R_{ta} f^{ah}.$$

Now, we contract (29) with f_{ih} , and from identity $f_{ih} R_k^h = \Phi_i^a R_{ka}$ we obtain:

$$2\Phi_i^a R_{ka} = \left(\frac{\tau^*}{2} + \tau \right) f_{ki} + \tau^* g_{ki} - \Phi_k^t R_{ti}$$

and

$$2\Phi_k^a R_{ia} = \left(\frac{\tau^*}{2} + \tau \right) f_{ki} + \tau^* g_{ki} - \Phi_i^t R_{tk}.$$

The last system of two equations implies

$$(30) \quad \Phi_k^a R_{ia} = \frac{1}{3} \left(\left(\frac{\tau^*}{2} + \tau \right) f_{ki} + \tau^* g_{ki} \right).$$

From (11) and (30) we find

$$(31) \quad \Phi_k^a R_{ia} f^{ij} = \frac{1}{3} \left(\left(\frac{\tau^*}{2} + \tau \right) \delta_k^j + \tau^* S_k^j \right).$$

After substituting (31) in (29), we get

$$R_k^h = \frac{\tau}{3} \delta_k^h + \frac{\tau^*}{6} \Phi_k^h,$$

and also

$$(32) \quad R_{ki} = \frac{\tau}{3}g_{ki} + \frac{\tau^*}{6}f_{ki}, \quad R_{ki}f^{ih} = \frac{\tau}{6}S_k^h + \frac{\tau^*}{6}\delta_k^h.$$

From the last equations we find that

$$\tau^* = -\tau.$$

That's why (32) becomes

$$(33) \quad R_{ki} = \frac{\tau}{6}(2g_{ki} - f_{ki}), \quad R_{ki}f^{ih} = \frac{\tau}{6}(S_k^h - \delta_k^h).$$

Finely we obtain:

$$R_{ijk}^h = \frac{\tau}{6}(2\delta_k^h g_{ij} - 2\delta_j^h g_{ki} + (\delta_k^h + S_k^h)f_{ij} - (\delta_j^h + S_j^h)f_{ki})$$

and

$$R_{hijk} = \frac{\tau}{6}(2g_{kh}g_{ij} - 2g_{hj}g_{ki} + f_{kh}f_{ij} - f_{hj}f_{ki}).$$

The last identity is equivalent to (23).

We note that $R_{ijk}^h \neq 0$, so ∇ isn't a locally flat connection. \square

Let p be a point in M and x, y be two linearly independent vectors in T_pM . It is known that

$$\mu(x, y) = \frac{R(x, y, x, y)}{g(x, x)g(y, y) - g^2(x, y)}$$

is the sectional curvature of the 2-section $\{x, y\}$.

Corollary 2.3. *Let M satisfy the conditions of Theorem 2.2. Let x be an arbitrary vector in T_pM , and φ be the angle between x and qx . Then, the sectional curvature of the 2-section $\{x, qx\}$ is*

$$\mu(x, qx) = -\frac{\tau}{6} \tan^2 \frac{\varphi}{2}, \quad \varphi \in (0, \frac{2\pi}{3}).$$

Corollary 2.4. *Let M satisfy the conditions of Theorem 2.2. Then, the Ricci tensor of g is degenerated.*

The proof follows from (33).

Note. Let $\{x, qx\}$ be a 2-section and $g(x, qx) = 0$. Then, $\mu(x, qx) = -\frac{\tau}{6}$.

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**ВЪРХУ АФИННИ СВЪРЗАНОСТИ В РИМАНОВО
МНОГООБРАЗИЕ С ЦИРКУЛАНТНА МЕТРИКА И ДВЕ
ЦИРКУЛАНТНИ АФИНОРНИ СТРУКТУРИ**

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В настоящата статия е разгледан клас V оттримерни риманови многообразия M с метрика g и два афинорни тензора q и S . Дефинирана е и друга метрика \bar{g} в M . Локалните координати на всички тези тензори са циркулантни матрици. Намерени са: 1) зависимост между тензора на кривина R породен от g и тензора на кривина \bar{R} породен от \bar{g} ; 2) твърдение за тензора на кривина \bar{R} в случая, когато тензорът на кривина R се анулира; 3) зависимост между секционната кривина на произволна двумерна q -площадка $\{x, qx\}$ и скаларната кривина на M .