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Abstract. Here the Dunkl operators $D_k f(x) = \dfrac{df(x)}{dx} + k\dfrac{f(x)-f(-x)}{x}$, $k > 0$, in $C^1(\mathbb{R})$ under a nonlocal boundary value condition $\Phi\{f\} = 0$ with an arbitrary non-zero linear functional Φ in $C(\mathbb{R})$ are considered. The right inverse operators L_k of D_k, defined by $D_k L_k f = f$ and $\Phi\{L_k f\} = 0$ are studied. To this end, the elements of corresponding operational calculi are developed. A convolution product $f * g$ on $C(\mathbb{R})$, such that $L_k f = \{1\} * f$, is found. Further, the convolution algebra $(C(\mathbb{R}), *)$ is extended to its ring $\mathfrak{M}_k$ of the multipliers. $(C(\mathbb{R}), *)$ may be conceived as a part of $\mathfrak{M}_k$ due to the embedding $f \hookrightarrow f*$. The ring $\mathcal{M}_k$ of multiplier fractions $\dfrac{P}{Q}$, such that $P, Q \in \mathfrak{M}_k$ and Q being non-divisor of zero in the operator multiplication, is constructed.
These operational calculi are used for effective solution of nonlocal Cauchy boundary value problems for *Dunkl functional-differential equations* $P(D_k)u = f$, where $\Phi(D_k^j u) = \alpha_j$ for $j = 0, 1, 2, \ldots, \deg P - 1$, with given constants α_j and a polynomial P. This is done by an extension of the Heaviside algorithm. The solution of Dunkl functional-differential equations $P(D_k) = f$ in mean-periodic functions reduces to such problems. Necessary and sufficient conditions for existence of unique solution in mean-periodic functions are found.
The operational calculus, developed here, is a generalization of the nonlocal operational calculus for $D_0 = \dfrac{d}{dx}$ (see Dimovski [5]). In a sense this paper is a continuation of our paper [6].

Key words: Dunkl operator; right inverse operator; Dunkl-Appell polynomials; convolution; multiplier; multiplier fraction; Dunkl equation; nonlocal Cauchy problem; mean-periodic function; Heaviside algorithm

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1 The right inverse operators of D_k in $C(\mathbb{R})$ and corresponding Taylor formulae

Let L_k denote an arbitrary right inverse operator of D_k in $C(\mathbb{R})$. First, we consider a special right inverse Λ_k of D_k, where $y(x) = \Lambda_k f(x)$ for $f \in C(\mathbb{R})$ is the solution of the equation $D_k y = f(x)$ with initial condition $y(0) = 0$.

It is easy to find that

$$\Lambda_k f(x) = \int_0^x \left[f_o(t) + \left(\frac{t}{x}\right)^{2k} f_e(t) \right] dt, \tag{1}$$

where f_e and f_o are the even and the odd parts of f, respectively .

Indeed, let $y(x) = \Lambda_k f(x)$ be represented as the sum of its even and odd parts, i.e. $y = y_e + y_o$. Then $D_k y(x) = f(x)$ can be written as

$$y_e' + y_o' + \frac{2k}{x} y_o = f_e + f_o$$

Separating the even and the odd parts gives:

$$\begin{aligned} y_o' + \frac{2k}{x} y_o &= f_e \\ y_e' &= f_o. \end{aligned}$$

Solving these similtaneous equations and taking into account the condition $y(0) = 0$ yields

$$y_e(x) = \int_0^x f_o(t)dt \qquad \text{and} \qquad y_o(x) = \int_0^x \left(\frac{t}{x}\right)^{2k} f_e(t)dt.$$

In the general case, an arbitrary right inverse operator L_k of D_k has a representation of the form

$$L_k f(x) = \int_0^x \left[f_e(t) + \left(\frac{t}{x}\right)^{2k} f_o(t) \right] dt + C.$$

In order L_k to be a linear operator, the additive constant C should depend on f and to be a linear functional $\Psi\{f\}$ in $C(\mathbb{R})$. Hence, an arbitrary linear right inverse operator L_k of D_k in $C(\mathbb{R})$ has the form

$$L_k f(x) = \Lambda_k f(x) + \Psi\{f\},$$

with a linear functional Ψ in $C(\mathbb{R})$.

According to the general theory of right invertible operators (Bittner [1], Przeworska-Rolewicz [12]), an important characteristic of L_k is its *initial projector*

$$F f(x) = f(x) - L_k D_k f(x) = \Phi\{f\}. \tag{2}$$

It maps $C^1(\mathbb{R})$ onto $\ker D_k = \mathbb{C}$, i.e. it is a linear functional Φ on $C^1(\mathbb{R})$. This identity written in the form

$$L_k D_k f(x) = f(x) - \Phi\{f\}. \tag{3}$$

will be used later. Expressing Φ by Ψ, we obtain

$$\Phi\{f\} = f(0) - \Psi\{D_k f\}.$$

Let us note that $\Phi\{1\} = 1$, which expresses the projector property of F.

Considering the right inverse operator L_k of D_k, it is more convenient to look on $L_k f = y$ as the solution of an elementary boundary value problem of the form

$$D_k y = f, \qquad \Phi\{y\} = 0, \tag{4}$$

assuming that Φ is a given linear functional on $C(\mathbb{R})$ with $\Phi\{1\} = 1$. This restriction of the class of right inverse operators L_k of D_k is adequate when we are to consider nonlocal Cauchy problems for Dunkl equations.

The simplest case of such an operator is when Φ is the Dirac functional $\Phi\{f\} = f(0)$. Then

$$L_k f(x) = \Lambda_k f(x) = \int_0^x \left[f_e(t) + \left(\frac{t}{x}\right)^{2k} f_o(t) \right] dt.$$

The general solution of (4) is

$$L_k f(x) = \int_0^x \left[f_e(y) + \left(\frac{y}{x}\right)^{2k} f_o(y) \right] dy - \Phi_t \left\{ \int_0^t \left[f_e(y) + \left(\frac{y}{t}\right)^{2k} f_o(y) \right] dy \right\}. \tag{5}$$

Definition 1. The *Dunkl-Appell polynomials* $\{A_{k,n}(x)\}_{n=0}^{\infty}$ are introduced by the recurrences

$$A_{k,0}(x) \equiv 1, \qquad \text{and} \qquad D_k A_{k,n+1}(x) = A_{k,n}(x), \quad \Phi\{A_{k,n+1}\} = 0, n \geq 0.$$

Lemma 1. *The Dunkl-Appell polynomials have the representation*

$$A_{k,n}(x) = L_k^n\{1\}(x), \quad n = 0, 1, 2, \ldots$$

where L_k is the right inverse (5) of the Dunkl operator D_k.

Proof. By induction. If $n = 0$, then $D_k A_{k,1}(x) = A_{k,0}(x) \equiv 1 \equiv L_k^0\{1\}(x)$ and therefore $A_{k,1}(x) = L_k\{1\}(x)$ since $\Phi\{A_{k,1}\} = 0$. Now, suppose that the assertion is true for $n \geq 0$. Then

$$D_k A_{k,n+1}(x) = L_k^n\{1\}(x) = A_{k,n}(x), \quad \Phi\{A_{k,n+1}\} = 0.$$

Hence $A_{k,n+1}(x) = L_k A_{k,n}(x) = L_k L_k^n\{1\}(x) = L_k^{n+1}\{1\}(x)$. ∎

Lemma 2. (Taylor formula with remainder term) *If $f \in C^{(n)}(\mathbb{R})$, then*

$$f(x) = \sum_{j=0}^{n-1} \Phi\{D_k^j f\} A_{k,j}(x) + L_k^n (D_k^n f)(x) \tag{6}$$

where $A_{k,j}(x) = L_k^j\{1\}(x)$ are the Dunkl-Appell polynomials.

This formula is an analogon of the particular case of the Taylor formula known as the Maclaurin formula.

Proof. Delsarte [3], Bittner [1], and Przeworska-Rolewicz [12] give variants of the Taylor formula for right invertible operators in linear spaces. In our case (6) can be written as

$$I = \sum_{j=0}^{n-1} L_k^j F D_k^j + L_k^n D_k^n$$

where I is the identity operator and $F = I - L_k D_k$. In functional form the above equality takes the form

$$f(x) = \sum_{j=0}^{n-1} L_k^j F D_k^j f(x) + L_k^n D_k^n f(x)$$

where the initial projector F of L_k (2) is the linear functional Φ:

$$Ff(x) = f(x) - L_k D_k f(x) = \Phi\{f\}.$$

F projects the space $C(\mathbb{R})$ onto the space $\mathbb{C}$ of the constants. Hence the Taylor formula (6) for the Dunkl operator D_k with remainder term is

$$f(x) = \sum_{j=0}^{n-1} \Phi\{D_k^j f\} L_k^j\{1\}(x) + L_k^n D_k^n f(x).$$ ∎

2 Convolutional products for the right inverses L_k of D_k

In Dunkl [9], Theorem 5.1, the similarity operator

$$V_k f(x) = b_k \int_{-1}^{1} f(xy)(1-y)^{k-1}(1+y)^k dy, \qquad b_k = \frac{\Gamma(2k+1)}{2^{2k}\Gamma(k)\Gamma(k+1)} \tag{7}$$

is found, which transforms the differentiation operator $D = \dfrac{d}{dx}$ into D_k:

$$V_k D = D_k V_k.$$

Usually this operator is called *intertwining operator.*

Denoting $Sf(x) = \dfrac{1}{2x}\dfrac{df(x)}{dx}$, the inverse V_k^{-1} of V_k (see Salem and Kallel [2]) has the following representations:

(i) If $k = n + r$ is non-integer with integer part $n = [k]$ and $r \in (0,1)$, then

$$\begin{aligned} V_k^{-1} f(x) &= c_k \left[|x| S^{n+1} \left\{ \int_0^{|x|} (x^2 - y^2)^{-r} f_e(y) y^{2k} dy \right\} \right. \\ &+ \left. \operatorname{sign}(x) S^{n+1} \left\{ \int_0^{|x|} (x^2 - y^2)^{-r} f_o(y) y^{2k+1} dy \right\} \right], \quad x \neq 0, \end{aligned}$$

where $c_k = \dfrac{2\sqrt{\pi}}{\Gamma\left(n + r + \frac{1}{2}\right)\Gamma(1-r)}$.

(ii) If $k \in \mathbb{N}_0 = \{0, 1, 2, \dots\}$, then

$$V_k^{-1} f(x) = \frac{\sqrt{\pi}}{\Gamma\left(k + \frac{1}{2}\right)} [x S^k (x^{2k-1} f_e(x)) + S^k (x^{2k} f_o(x))], \quad x \neq 0.$$

V_k transforms $C(\mathbb{R})$ into a proper subspace $\widetilde{C_k} = V_k(C(\mathbb{R}))$ of it. V_k is a similarity from a right inverse operator Λ of $D_0 = \dfrac{d}{dx}$ to L_k. In order to specify the operator Λ let us define the linear functional

$$\widetilde{\Phi}\{f\} = (\Phi \circ V_k)\{f\} \tag{8}$$

in $\widetilde{C_k}$. Then define $\Lambda : \widetilde{C_k} \to \widetilde{C_k}$ to be the solution $y = \Lambda \widetilde{f}$ of the elementary boundary value problem

$$D_0 y(x) \equiv y'(x) = \widetilde{f}(x), \qquad \widetilde{\Phi}\{y\} = 0.$$

This solution has the form

$$\Lambda \widetilde{f}(x) = \int_0^x \widetilde{f}(y) dy - \widetilde{\Phi}_t \left\{ \int_0^t \widetilde{f}(\tau) d\tau \right\}. \tag{9}$$

Lemma 3. *The following similarity relation holds*

$$V_k \Lambda = L_k V_k.$$

Proof. Applying V_k to the defining equation $D(\Lambda \widetilde{f}) = \widetilde{f}$, one obtains

$$V_k D(\Lambda \widetilde{f}) = V_k \widetilde{f} = f$$

or

$$D_k(V_k\Lambda\widetilde{f}) = V_k\widetilde{f} = f.$$

In fact, the boundary value condition $\widetilde{\Phi}\{\Lambda\widetilde{f}\} = 0$ can be written as $\Phi\{V_k\Lambda\widetilde{f}\} = 0$. Hence $u = V_k\Lambda\widetilde{f}$ is the solution of the boundary value problem $D_k u = f$, $\Phi\{u\} = 0$, i.e. $u = L_k f$. Therefore

$$V_k\Lambda V_k^{-1} f = L_k f \qquad \text{or} \qquad V_k\Lambda = L_k V_k. \qquad \blacksquare$$

The similarity relation (3) allows to introduce a convolution structure $* : C(\mathbb{R}) \times C(\mathbb{R}) \to C(\mathbb{R})$, such that L_k to be the convolution operator $L_k = \{1\}*$ in $C(\mathbb{R})$.

The operator Λ is defined not only in $\widetilde{C_k}$, but in the whole space $C(\mathbb{R})$. This allows to introduce a convolution structure $\widetilde{*} : C(\mathbb{R}) \times C(\mathbb{R}) \to C(\mathbb{R})$.

Lemma 4. *The operation*

$$(\widetilde{f}\widetilde{*}\widetilde{g})(x) = \widetilde{\Phi}_t\left\{\int_t^x \widetilde{f}(x+t-\tau)\widetilde{g}(\tau)d\tau\right\} \tag{10}$$

is an inner operation in $\widetilde{C_k} = V_k(C(\mathbb{R}))$ *such that*

$$\Lambda\widetilde{f} = \{1\}\widetilde{*}\widetilde{f}. \tag{11}$$

It satisfies the boundary value condition $\widetilde{\Phi}\{\widetilde{f} * \widetilde{g}\} = 0$ *for arbitrary* $\widetilde{f}$ *and* $\widetilde{g}$ *in* $C(\mathbb{R})$.

The proof of the first part follows directly from the explicit inversion formula for V_k (see Salem and Kallel [2], Theorem 1.1). The second relation (11) is obvious. The proof of $\widetilde{\Phi}\{\widetilde{f} * \widetilde{g}\} = 0$ is also elementary (see Dimovski [4], p. 54).

Theorem 1. *The operation*

$$f * g = D_k^{2n} V_k[(V_k^{-1}L_k^n f)\widetilde{*}(V_k^{-1}L_k^n g)] \tag{12}$$

where $n = [k]$ *is the integer part of* k *is a convolution of* L_k *in* $C(\mathbb{R})$ *such that*

$$L_k f = \{1\} * f. \tag{13}$$

and satisfying the boundary value condition $\Phi\{f * g\} = 0$ *for arbitrary* f *and* g *in* $C(\mathbb{R})$.

Proof. The assertion of the theorem follows from Lemmas 4 and 3 and a general theorem of Dimovski [4], Theorem 1.3.6, p. 20. This convolution is introduced in Dimovski, Hristov and Sifi [6]. $\blacksquare$

From (13) it follows that

$$L_k^{n+1} f = \{A_{k,n}\} * f,$$

where $A_{k,n}$ is the Dunkl-Appell polynomial of degree exactly n. This allows also to state the Taylor formula (6) with remainder term in the Cauchy form:

Lemma 5. *If* $f \in C^{(n)}(\mathbb{R})$, *then*

$$f(x) = \sum_{j=0}^{n-1} \Phi\{D_k^j f\} A_{k,j}(x) + (A_{k,n-1} * D_k^n f)(x),$$

where $A_{k,j}(x)$, $j = 0, 1, 2, \ldots, n-1$, *are the Dunkl-Appell polynomials* $A_{k,j}(x) = L_k^j\{1\}$.

3 Mean-periodic functions for D_k determined by a linear functional

The notion of mean-periodic function for the differentiation operator $\frac{d}{dt}$, determined by a linear functional Φ in $C(\mathbb{R})$, is introduced by J. Delsarte [3]:

A function $f \in C(\mathbb{R})$ is said to be *mean-periodic with respect to the functional* Φ if it satisfies identically the condition

$$\Phi_\tau\{f(t+\tau)\} = 0. \tag{14}$$

In order to define mean-periodic function for the Dunkl operator D_k we need to remind the definition of the Dunkl translation (shift) operators, introduced by M. Rösler [13]. They are a class of operators $M : C(\mathbb{R}) \to C(\mathbb{R})$ commuting with D_k in $C^1(\mathbb{R})$.

Definition 2. Let $f \in C(\mathbb{R})$ and $y \in \mathbb{R}$. Then $(T_k^y f)(x) = u(x,y) \in C^1(\mathbb{R}^2)$ is the solution of the boundary value problem

$$D_{k,x}u(x,y) = D_{k,y}u(x,y), \qquad u(x,0) = f(x). \tag{15}$$

T_k^y is called the *translation operator for the Dunkl operator* D_k.

Such a solution exists for arbitrary $f \in C(\mathbb{R})$ and it has the following explicit form (see e.g. [13], [2]):

$$\begin{aligned} T_k^y f(x) &= \frac{\Gamma\left(k+\frac{1}{2}\right)}{\Gamma(k)\Gamma\left(\frac{1}{2}\right)} \left[\int_0^\pi f_e\left(\sqrt{x^2+y^2-2|xy|\cos t}\right) h^e(x,y,t)\sin^{2k-1} t\,dt\right. \\ &+ \left.\int_0^\pi f_o\left(\sqrt{x^2+y^2-2|xy|\cos t}\right) h^o(x,y,t)\sin^{2k-1} t\,dt\right]. \end{aligned}$$

As usually, the subscripts "e" and "o" denote correspondingly the even and the odd part of a function: $f_e(x) = \frac{f(x)+f(-x)}{2}$, $f_o(x) = \frac{f(x)-f(-x)}{2}$. As for $h^e(x,y,t)$ and $h^o(x,y,t)$, they denote respectively

$$\begin{aligned} h^e(x,y,t) &= 1 - \operatorname{sign}(xy)\cos t, \\ h^o(x,y,t) &= \begin{cases} \dfrac{(x+y)(1-\operatorname{sign}(xy)\cos t)}{\sqrt{x^2+y^2-2|xy|\cos t}} & \text{for } (x,y) \neq (0,0), \\ 0 & \text{otherwise.} \end{cases} \end{aligned}$$

Lemma 6. *The translation operators satisfy the following basic relations:*

$$\text{(i)} \quad T_k^y f(x) = T_k^x f(y) \tag{16}$$

$$\text{(ii)} \quad T_k^y T_k^z f(x) = T_k^z T_k^y f(x) \tag{17}$$

$$\text{(iii)} \quad D_{k,x} T_k^y f(x) = T_k^y D_{k,x} f(x). \tag{18}$$

Proofs can be found in various publications, in particular, in our paper [6].

A natural extension of the notion of mean-periodic function for the Dunkl operator is proposed by Salem and Kallel [2]. Instead of (14) they use the condition

$$\Phi_y\{T_k^y f(x)\} = 0 \tag{19}$$

to define *mean-periodic function* f *for* D_k *with respect to the functional* Φ. Here T_k^y is the generalized translation operator just defined. The notation MP_Φ will be used for the spaces of these mean-periodic functions in $C(\mathbb{R})$ without using additional subscript k for the sake of simplicity.

Lemma 7. *If $f \in MP_\Phi$, then $L_k f \in MP_\Phi$.*

Proof. Denote $\varphi(x) = \Phi_t\{T_k^t L_k f(x)\}$ and use the commutation relation (18) from Lemma 6 $D_{k,x}T_k^y f(x) = T_k^y D_{k,x} f(x)$ to obtain

$$D_k\varphi(x) = \Phi_t\{D_k T_k^t L_k f(x)\} = \Phi_t\{T_k^t D_k L_k f(x)\} = \Phi_t\{T_k^t f(x)\} = 0.$$

Hence $\varphi(x) = C = \text{const}$. But $\varphi(0) = \Phi_t\{T_k^t L_k f(0)\} = \Phi_t\{T_k^0 L_k f(t)\} = \Phi_t\{L_k f(t)\} = 0$. Hence $C = 0$. ∎

Further we will be interested in the solvability of Dunkl differential-difference equations

$$P(D_k)u = f \tag{20}$$

with a polynomial P in the space of the mean-periodic functions MP_Φ, defined by (19). We intend also to propose an algorithm for obtaining such solutions.

To this end we are to develop an operational calculus for D_k in $C(\mathbb{R})$ and to extend the Heaviside algorithm for it. The following result plays a basic role in the application of this algorithm for solution of Dunkl equations in mean-periodic functions.

Theorem 2. *The class of mean-periodic functions MP_Φ is an ideal in the convolutional algebra $(C(\mathbb{R}), *)$, i.e. if $f \in MP_\Phi$ and $g \in C(\mathbb{R})$, then $f * g \in MP_\Phi$.*

Proof. Assume that $f \in MP_\Phi$, i.e.

$$\Phi_t\{T_k^t f(x)\} = 0.$$

From Lemma 7 it follows that $L_k^{n+1} f \in MP_\Phi$ for $n = 0, 1, 2, \ldots$, i.e.

$$\Phi_t\{T_k^t L_k^{n+1} f(x)\} = 0.$$

Since $L_k f = \{1\} * f$, then $L_k^{n+1} f = A_{k,n} * f$, where the Dunkl-Appell polynomial $A_{k,n}$ is of degree exactly n. We have

$$\Phi_t\{T_k^t(A_{k,n} * f)(x)\} = 0$$

and then we can assert that

$$\Phi_t\{T_k^t(P * f)(x)\} = 0$$

for any polynomial P. By an approximation argument it follows that

$$\Phi_t\{T_k^t(g * f)(x)\} = 0$$

for arbitrary $g \in C(\mathbb{R})$, i.e. that $g * f \in MP_\Phi$. ∎

4 The ring of multipliers of the convolutional algebra $(C(\mathbb{R}), *)$

The convolutional algebras $(C(\mathbb{R}), *)$ with convolution product (12), are annihilators-free (or algebras without order in the terminology of Larsen [10], p. 13). This means that in each of these algebras $f * g = 0$, $\forall g \in C(\mathbb{R})$, implies $f = 0$.

Definition 3. An operator $A : C(\mathbb{R}) \to C(\mathbb{R})$ is said to be a *multiplier of the convolutional algebra* $(C(\mathbb{R}), *)$ iff

$$A(f * g) = (Af) * g \tag{21}$$

for arbitrary $f, g \in C(\mathbb{R})$.

As it is shown in Larsen [10], it is not necessary to assume neither that A is a linear operator, nor that it is continuous in $C(\mathbb{R})$. These properties of the multipliers follow automatically from (21). Something more, a general result of Larsen [10], p.13, implies

Theorem 3. *The set of the multipliers of the convolutional algebra $(C(\mathbb{R}), *)$ form a commutative ring $\mathfrak{M}_k$.*

The simplest multipliers of $(C(\mathbb{R}), *)$ are the numerical operators $[\alpha]$ for $\alpha \in \mathbb{C}$, defined by

$$[\alpha]f = \alpha f, \quad \forall f \in C(\mathbb{R}), \tag{22}$$

and the convolutional operators $f*$ for $f \in C(\mathbb{R})$, defined by

$$(f*)g = f * g, \quad \forall g \in C(\mathbb{R}). \tag{23}$$

Further we need the following characterization result for the multipliers of $(C(\mathbb{R}), *)$:

Theorem 4. *A linear operator $A : C(\mathbb{R}) \to C(\mathbb{R})$ is a multiplier of $(C(\mathbb{R}), *)$ iff it admits a representation of the form*

$$Af = D_k(m * f), \tag{24}$$

where the function $m = A\{1\}$ is such that $m * f \in C^1(\mathbb{R})$ for all $f \in C(\mathbb{R})$.

Proof. Let $A : C(\mathbb{R}) \to C(\mathbb{R})$ be a multiplier of $(C(\mathbb{R}), *)$. The operator $L_k f = \{1\} * f$ is also a multiplier. Then, according to Theorem 3,

$$AL_k = L_k A.$$

Applying A to $L_k f = \{1\} * f$, we get

$$L_k A f = AL_k f = A(\{1\} * f) = (A\{1\}) * f.$$

The identity

$$L_k(Af) = m * f \tag{25}$$

with $m = A\{1\}$ is possible only if $m * f \in C^1(\mathbb{R})$ for each $f \in C(\mathbb{R})$. It remains to apply D_k to (25) in order to obtain (24).

Conversely, let $A : C(\mathbb{R}) \to C(\mathbb{R})$ be the operator defined by (24), i.e. $Af = D_k(m * f)$, where $m \in C(\mathbb{R})$ is such that $m * f \in C^1(\mathbb{R})$ for all $f \in C(\mathbb{R})$. Then

$$A(f * g) = D_k(m * (f * g)) = D_k((m * f) * g).$$

But $m * f = L_k D_k(m * f)$ due to formula (3) since $\Phi(m * f) = 0$ by Theorem 1. Then

$$A(f * g) = D_k L_k[D_k(m * f) * g] = (Af) * g.$$

Hence A is a multiplier of the convolution algebra $(C(\mathbb{R}), *)$. ■

The specification of the function $m = A\{1\}$ is, in general, a nontrivial problem even in the case of the simplest Dunkl operator $D_0 = \frac{d}{dx}$ (the usual differentiation). This could be confirmed by the following two examples:

Example 1. If $\Phi\{f\} = f(0)$, then m is a continuous function of locally bounded variation, i.e. $m \in BV \cap C(\mathbb{R})$ (see Dimovski [4], p. 26).

Example 2. Let $\Phi\{f\} = \int_0^1 f(x)dx$. Then $m \in C(\mathbb{R})$ can be arbitrary.

Corollary 1. *Let $M : C(\mathbb{R}) \to C(\mathbb{R})$ be an arbitrary multiplier of the algebra $(C(\mathbb{R}), *)$. Then $M(MP_\Phi) \subset MP_\Phi$, i.e. the restriction of M to MP_Φ is an inner operator in MP_Φ.*

Proof. Let $f \in MP_\Phi$. Since $MP_\Phi = D_k(m * f)$ with $m = M\{1\}$, then, by Theorem 2, $m * f \in MP_\Phi \cap C^1(\mathbb{R})$. Then $D_k(m * f) \in MP_\Phi$, i.e. $f \in MP_\Phi$ implies $Mf \in MP_\Phi$. ■

5 Nonlocal operational calculi

Our aim here is to develop a direct operational calculus for solution of the following *nonlocal Cauchy problem* for the operator D_k: Solve the equation $P(D_k)u = f$ with a polynomial P and a given $f \in C(\mathbb{R})$ under the boundary value conditions $\Phi\{D_k^j u\} = \alpha_j$, $j = 0, 1, 2, \dots, \deg P - 1$, where α_j are given constants and Φ is a nonzero linear functional on $C(\mathbb{R})$.

This is a special case of the problems considered by R. Bittner [1] and D. Przeworska-Rolewicz [12] for an arbitrary right invertible operator D instead of D_k.

Our intention here is to propose constructive results and to obtain an explicit solution of the boundary value problems considered. This is done by means of an operational calculus essential part of which is an extension of the Heaviside algorithm.

This operational calculus is developed using a direct algebraic approach based on the convolution (12). Instead of Mikusiński's method [11] of convolutional fractions $\frac{f}{g}$, we follow an alternative approach of multiplier fractions $\frac{A}{B}$, where A and B are multipliers of the convolution algebra $(C(\mathbb{R}), *)$ in the ring of the multipliers $\mathfrak{M}_k$, i.e. $A, B \in \mathfrak{M}_k$ and B is a non-divisor of zero in the operator multiplication.

The nonlocal Cauchy problems arise in a quite natural way when we are looking for mean-periodic solutions of Dunkl equations. Each mean-periodic solution of the equation $P(D_k)u = f$ satisfies the homogeneous boundary value conditions $\Phi\{D_k^j u\} = 0$, $j = 0, 1, 2, \dots, \deg P - 1$ and it may be obtained explicitly.

Let us consider the ring $\mathfrak{M}_k$ of the multipliers of the convolutional algebra $(C(\mathbb{R}), *)$. The correspondence $\alpha \mapsto [\alpha]$ is an embedding of $\mathbb{C}$ into $\mathfrak{M}_k$. The correspondence $f \mapsto f*$ is an embedding of $(C(\mathbb{R}), *)$ in $\mathfrak{M}_k$. Hence, we may consider $\mathbb{C}$ and $C(\mathbb{R})$ as parts of $\mathfrak{M}_k$.

$\mathfrak{M}_k$ is a commutative ring (Theorem 3). The subset $\mathfrak{N}_k$ of $\mathfrak{M}_k$, consisting of the non-zero non-divisors of zero with respect to the operator multiplication in $\mathfrak{M}_k$, is nonempty. Indeed, at least the identity operator I and the right inverse L_k of D_k belong to $\mathfrak{N}_k$. In addition, $\mathfrak{N}_k$ is a multiplicative subset, i.e. if $A, B \in \mathfrak{N}_k$, then $AB \in \mathfrak{N}_k$.

Consider the Cartesian product

$$\mathfrak{M}_k \times \mathfrak{N}_k = \{(A, B) : A \in \mathfrak{M}_k, B \in \mathfrak{N}_k\}$$

and introduce the equivalence relation

$$(A, B) \sim (A', B') \Leftrightarrow AB' = BA'. \tag{26}$$

Definition 4. The set $\mathcal{M}_k = \mathfrak{M}_k \times \mathfrak{N}_k/\sim$ obtained by factorization of $\mathfrak{M}_k \times \mathfrak{N}_k$ with respect to the equivalence relation (26) is said to be the *ring of multiplier fractions*.

$\mathcal{M}_k$ may be considered both as an extension of the field $\mathbb{C}$ of the complex numbers and of the ring $(C(\mathbb{R}), *)$. Formally, this is seen by the embeddings

$$\alpha \hookrightarrow \frac{[\alpha]}{I} \quad \text{and} \quad f \hookrightarrow \frac{f*}{I}.$$

In the sequel we denote the identity operator I simply by 1. The multiplication operation of the two elements P and Q in $\mathcal{M}_k$ will be denoted simply by PQ. Therefore, instead of $f * g$ we will write fg.

For our aims the most important elements of $\mathcal{M}_k$ are

$$L_k = \{1\} \quad \text{and} \quad S_k = \frac{1}{L_k}.$$

The fraction S_k with the identity operator as numerator and with L_k as denominator will be called *algebraic Dunkl operator*. Its relation to the ordinary Dunkl operator D_k is given by the following theorem:

Theorem 5. *Let $f \in C^1(\mathbb{R})$. Then*

$$D_k f = S_k f - \Phi\{f\}. \tag{27}$$

Note that identity (27) should be interpreted as

$$(D_k f)* = S_k(f*) - [\Phi\{f\}],$$

where $(D_k f)*$ and $(f*)$ are to be understood as convolution operators and $[\Phi\{f\}]$ as the numerical operator determined by the number $\Phi\{f\}$. S_k is neither convolutional nor numerical operator, but an element of $\mathcal{M}_k$.

Proof. In Section 1 (equality (3)) we have seen that

$$L_k D_k f = f - \Phi\{f\},$$

where $\Phi\{f\}$ is the corresponding constant function $\{\Phi\{f\}\}$. Considered as an operator identity, this can be written as $(L_k D_k f)* = f * -\{\Phi\{f\}\}*$ or $L_k[D_k(f*)] = f * -\Phi\{f\}.L_k$. Hence

$$L_k(D_k f)* = (f*) - \Phi\{f\}L_k.$$

It remains to multiply by S_k to obtain (27). ∎

Relation (27) may be characterized as the basic formula of our operational calculus. Using it repeatedly, we obtain

Corollary 2. *Let $f \in C^{(n)}(\mathbb{R})$. Then*

$$D_k^n f = S_k^n f - \sum_{j=0}^{n-1} \Phi\{D_k^j f\} S_k^{n-j-1}. \tag{28}$$

Remark 1. The last formula is equivalent to the Taylor formula (6) in Section 1.

By means of (27) and (28) it is possible to "algebraize" the nonlocal Cauchy boundary value problem

$$P(D_k)u = f, \qquad \Phi\{D_k^j u\} = \alpha_j,\ j = 0, 1, 2, \dots, m-1,$$

where $P(\lambda) = a_0\lambda^m + a_1\lambda^{m-1} + \dots + a_{m-1}\lambda + a_m$, $a_0 \neq 0$, and Φ is a non-zero linear functional on $C(\mathbb{R})$.

Definition 5. The problem for solving the Dunkl functional-differential equation

$$P(D_k)u = f, \qquad f \in C(\mathbb{R})$$

under the boundary value conditions

$$\Phi\{D_k^j u\} = \alpha_j,\ j = 0, 1, 2, \dots, m-1$$

is called a *nonlocal Cauchy problem determined by the functional* Φ.

The simplest nonlocal Cauchy problem for D_k, determined by a linear functional Φ in $C(\mathbb{R})$ concerns the functional-differential equation

$$D_k u(x) - \lambda u(x) = f(x) \tag{29}$$

with the boundary condition $\Phi\{u\} = 0$.

It is known that the solution of the homogeneous equation

$$D_k u(x) - \lambda u(x) = 0$$

under the initial condition $u(0) = 1$ is

$$u_k(\lambda x) = j_{k-\frac{1}{2}}(i\lambda x) + \frac{\lambda x}{2k+1} j_{k+\frac{1}{2}}(i\lambda x) \tag{30}$$

(see Salem and Kallel [2], p.161), where $j_\alpha(x)$ denotes the modified (normalized) Bessel function

$$j_\alpha(x) = 2^\alpha \Gamma(\alpha+1)\frac{J_\alpha(x)}{x^\alpha}, \qquad x \neq 0 \text{ and } j_\alpha(0) = 1.$$

We introduce the *Dunkl indicatrix* of the functional Φ as the following entire function of exponential type:

$$E_k(\lambda) = \Phi_\xi\{u_k(\lambda\xi)\} = \Phi_\xi\left\{ j_{k-\frac{1}{2}}(i\lambda\xi) + \frac{\lambda\xi}{2k+1} j_{k+\frac{1}{2}}(i\lambda\xi)\right\}. \tag{31}$$

The linear operator $L_{k,\lambda}$ defined as the solution $u(x) = L_{k,\lambda} f(x)$ of the nonlocal Cauchy boundary value problem

$$D_k u - \lambda u = f, \qquad \Phi\{u\} = 0,$$

is said to be the *resolvent operator of the Dunkl operator* under the boundary value condition $\Phi\{u\} = 0$.

Theorem 6. *The resolvent operator $L_{k,\lambda}$ admits the convolutional representation*

$$L_{k,\lambda} f(x) = l_k(\lambda, x) * f(x), \quad \text{where} \quad l_k(\lambda, x) = \frac{u_k(\lambda x)}{E_k(\lambda)}. \tag{32}$$

Proof. We will use the formula

$$D_k(f * g) = (D_k f) * g + \Phi\{f\} g$$

which is true under the assumption $f \in C^1(\mathbb{R})$. It follows from a more general result of Dimovski [4], Th. 1.38, but in our case it can be verified directly. It gives

$$D_k\{l_k(\lambda, x) * f(x)\} = D_k l_k(\lambda, x) * f(x) + \Phi_\xi\{l_k(\lambda, \xi)\} f(x) = \lambda\{l_k(\lambda, x) * f(x)\} + f(x).$$

Hence $u = \{l_k(\lambda, x) * f(x)\}$ satisfies the equation $D_k u - \lambda u = f$. It remains to verify the boundary value condition $\Phi\{u\} = 0$. But it follows from the basic property $\Phi\{f * g\} = 0$ of the convolution (Theorem 1). ■

The resolvent operator $L_{k,\lambda}$ exists for each λ with $E_k(\lambda) \neq 0$. The zeros of $E_k(\lambda)$ are the eigenvalues of the boundary value problem $D_k u - \lambda u = 0$, $\Phi\{u\} = 0$. They form an enumerable set $\{\lambda_1, \lambda_2, \ldots, \lambda_n, \ldots\}$ except in the case when Φ is a Dirac functional $\Phi\{f\} = f(a)$, when $E_k(\lambda) \neq 0$ for all $\lambda \in \mathbb{C}$.

It is easy to find the solution of our problem in $\mathcal{M}_k$. Using the basic formula of the operational calculus (see Theorem 5), we have $D_k u = S_k u$ since $\Phi\{u\} = 0$, and then

$$S_k u - \lambda u = f \qquad \text{or} \qquad (S_k - \lambda)u = f.$$

In order to write the solution

$$u = \frac{1}{S_k - \lambda} f$$

we must be sure that $S_k - \lambda$ is non-divisor of zero.

Lemma 8. *$S_k - \lambda$ is a divisor of zero in $\mathcal{M}_k$ iff $E_k(\lambda) = 0$.*

Proof. Let $S_k - \lambda$ be a divisor of zero in $\mathcal{M}_k$. Then there exists a multiplier fraction $\frac{A}{B}$ such that $A \neq 0$ and

$$(S_k - \lambda)\frac{A}{B} = 0,$$

which is equivalent to $(S_k - \lambda)A = 0$. Since $A \neq 0$, then there is a function $g \in C(\mathbb{R})$ such that $Ag = v \neq 0$. Then

$$(S_k - \lambda)v = 0.$$

Multiplying by L_k we get

$$(1 - \lambda L_k)v = 0 \qquad \text{or} \qquad v - \lambda L_k v = 0.$$

Since $\Phi(L_k v) = 0$ by the definition of L_k (Section 1), then $\Phi\{v\} = 0$.

Applying D_k, we get $D_k v - \lambda v = 0$, $\Phi\{v\} = 0$. According to Salem and Kallel [2], all the non-zero solutions of $D_k v - \lambda v = 0$ are $v = C(j_{k-\frac{1}{2}}(i\lambda x) + \frac{\lambda x}{2k+1} j_{k+\frac{1}{2}}(i\lambda x))$ with a constant $C \neq 0$. The boundary value condition $\Phi\{v\} = 0$ is equivalent to $E_k(\lambda) = 0$.

Conversely, if $E_k(\lambda) = 0$, then there exists a solution $v \neq 0$ of the eigenvalue problem $D_k v - \lambda v = 0$, $\Phi\{v\} = 0$. For this v we have

$$(S_k - \lambda)v = 0$$

and hence $S_k - \lambda$ is a divisor of zero in $\mathcal{M}_k$. ■

Theorem 7. *Let $\lambda \in \mathbb{C}$ be such that $E_k(\lambda) \neq 0$. Then*

$$\frac{1}{S_k - \lambda} = \{l_k(\lambda, x)\}* = \frac{1}{E_k(\lambda)} \left\{ j_{k-\frac{1}{2}}(i\lambda x) + \frac{\lambda x}{2k+1} j_{k+\frac{1}{2}}(i\lambda x) \right\} * . \tag{33}$$

Proof. We have seen that

$$L_{k,\lambda} f(x) = \{l_k(\lambda, x)\} * f.$$

But for the solution $u = L_{k,\lambda} f$ of the boundary value problem $D_k u - \lambda u = f$, $\Phi\{u\} = 0$, in the case $E_k(\lambda) \neq 0$ we found

$$u = \frac{1}{S_k - \lambda} f.$$

Since the convolution $*$ is annihilators-free, then (33) follows from the identity

$$\frac{1}{S_k - \lambda} f = \{l_k(\lambda, x)\} * f.$$

■

Corollary 3. *If $E_k(\lambda) \neq 0$, then*

$$\frac{1}{(S_k - \lambda)^m} = \left\{ \frac{1}{(m-1)!} \frac{\partial^{m-1}}{\partial \lambda^{m-1}} l_k(\lambda, x) \right\} * . \tag{34}$$

6 Heaviside algorithm for solving nonlocal Cauchy problems for Dunkl operators

Now we are to apply the elements of the operational calculus developed in the previous section to effective solution of nonlocal Cauchy boundary value problems of the form

$$P(D_k)u = f, \quad \Phi(D_k^j u) = \alpha_j, \ j = 0, 1, 2, \ldots, \deg P - 1, \tag{35}$$

with given $\alpha_j \in \mathbb{C}$.

To this end we extend the classical Heaviside algorithm, which is intended for solving initial value problems for ordinary linear differential equations with constant coefficients to the case of Dunkl functional-differential equations.

The extended Heaviside algorithm starts with the algebraization of problem (35). It reduces the problem to a single algebraic equation of the first degree in $\mathcal{M}_k$.

Let $P(\lambda) = a_0\lambda^m + a_1\lambda^{m-1} + \cdots + a_{m-1}\lambda + a_m$ be a given polynomial of m-th degree, i.e. with $a_0 \neq 0$.

The consecutive steps of the algorithm are the following:

1) Factorize $P(\lambda)$ in $\mathbb{C}$ to

$$P(\lambda) = a_0(\lambda - \mu_1)^{\varkappa_1}(\lambda - \mu_2)^{\varkappa_2} \ldots (\lambda - \mu_s)^{\varkappa_s},$$

where $\mu_1, \mu_2, \ldots, \mu_s$ are the distinct zeros of $P(\lambda)$ and $\varkappa_1, \varkappa_2, \ldots, \varkappa_s$ are their corresponding multiplicities.

2) Represent each of the terms of the equation by the the algebraic Dunkl operator S_k. This is done by the formulae

$$D_k^j u = S_k^j u - S_k^{j-1}\alpha_0 - S_k^{j-2}\alpha_1 - \cdots - S_k\alpha_{j-2} - \alpha_{j-1}\,, \quad j = 1, 2, \ldots, m.$$

Thus we obtain the following equation in $\mathcal{M}_k$:

$$P(S_k)u = f + Q(S_k), \quad \deg Q < \deg P, \tag{36}$$

with

$$Q(S_k) = \sum_{j=0}^{m-1}\sum_{l=0}^{m-j-1} a_j\alpha_l S_k^{m-j-l-1} = \sum_{\mu=0}^{m-1}\left(\sum_{\nu=0}^{m-\mu-1} a_\nu\alpha_{m-\mu-\nu-1}\right) S_k^\mu.$$

3) Verify if $P(S_k)$ is a non-divisor of zero in $\mathcal{M}_k$ by checking if $E_k(\mu_j) \neq 0$ for all $j = 1, 2, \ldots, s$.

4) If $P(S_k)$ is a non-divisor of zero, then write the solution u in $\mathcal{M}_k$:

$$u = \frac{1}{P(S_k)}f + \frac{Q(S_k)}{P(S_k)}.$$

5) Expand $\dfrac{1}{P(S_k)}$ and $\dfrac{Q(S_k)}{P(S_k)}$ into partial fractions:

$$\frac{1}{P(S_k)} = \sum_{j=1}^{s}\sum_{l=1}^{\varkappa_j}\frac{A_{j,l}}{(S_k - \mu_j)^l},$$

$$\frac{Q(S_k)}{P(S_k)} = \sum_{j=1}^{s}\sum_{l=1}^{\varkappa_j}\frac{B_{j,l}}{(S_k - \mu_j)^l}.$$

6) Interpret the partial fractions as convolution operators

$$\frac{1}{S_k-\mu_j} = \{l_k(\mu_j,x)\}* = \frac{1}{E_k(\mu_j)}\left\{j_{k-\frac{1}{2}}(i\mu_j x) + \frac{\mu_j x}{2k+1} j_{k+\frac{1}{2}}(i\mu_j x)\right\}*.$$

$$\frac{1}{(S_k-\mu_j)^l} = \left\{\frac{1}{(l-1)!}\frac{\partial^{l-1}}{\partial\lambda^{l-1}} l_k(\lambda,x)\bigg|_{\lambda=\mu_j}\right\}*, \quad l=2,3,\ldots.$$

7) Write the convolutional representation

$$u(x) = (G*f)(x) + R(x), \quad \text{where} \quad G = \frac{1}{P(S_k)}, \; R = \frac{Q(S_k)}{P(S_k)}.$$

Example 3. Let $P(\lambda)$ has only simple zeros $\mu_1, \mu_2, \ldots, \mu_m$. Then

$$\frac{1}{P(S_k)} = \sum_{j=1}^{m} \frac{1}{P'(\mu_j)} \cdot \frac{1}{S_k-\mu_j} = \left\{\sum_{j=1}^{m} \frac{1}{P'(\mu_j)} l_k(\mu_j,x)\right\}*$$

and

$$\frac{Q(S_k)}{P(S_k)} = \sum_{j=1}^{m} \frac{Q(\mu_j)}{P'(\mu_j)} \cdot \frac{1}{S_k-\mu_j} = \left\{\sum_{j=1}^{m} \frac{Q(\mu_j)}{P'(\mu_j)} l_k(\mu_j,x)\right\}*.$$

Then the solution u takes the functional form

$$u(x) = \sum_{j=1}^{m} \frac{1}{P'(\mu_j)} l_k(\mu_j,x) * f(x) + \sum_{j=1}^{m} \frac{Q(\mu_j)}{P'(\mu_j)} l_k(\mu_j,x).$$

The result of this section can be summarized in the following

Theorem 8. *The nonlocal Cauchy problem* (Definition 5) *for a Dunkl equation* $P(D_k)u = f$ *has a unique solution in* $C^{(m)}(\mathbb{R})$, $m = \deg P$, *iff none of the zeros of the polynomial* $P(\lambda)$ *is a zero of the indicatrix* $E_k(\lambda)$, *i.e. when*

$$\{\lambda : P(\lambda)=0\} \cap \{\lambda : E_k(\lambda)=0\} = \emptyset.$$

Remark 2. The term "nonlocal" should not be understood literary. The assertion of Theorem 8 is true also when Φ is a Dirac functional, i.e. $\Phi\{f\} = f(a)$ for $a \in \mathbb{R}$. For us the most interesting is the case $\Phi\{f\} = f(0)$. Then $E_k(\lambda) \equiv 1$ and from the theorem it follows that the initial value problem

$$P(D_k)u = f, \quad u(0) = \alpha_0, (D_k u)(0) = \alpha_1, \ldots, (D_k^{n-1}u)(0) = \alpha_{n-1},$$

always has a unique solution. We will use this fact in the following section.

7 Mean-periodic solutions of Dunkl equations

Theorem 9. *A function* $u \in MP_\Phi \cap C^{(m)}(\mathbb{R})$ *is a solution of the Dunkl equation* $P(D_k)u = f$, *provided* $f \in MP_\Phi$ *and* u *is a solution of the homogeneous nonlocal Cauchy problem*

$$P(D_k)u = f, \quad \Phi\{D_k^j u\} = 0, \; j = 0,1,2,\ldots,m-1, \; m = \deg P.$$

Proof. The condition $f \in MP_\Phi$ is necessary for the existence of a solution $u \in MP_\Phi$. Assume that a function $u \in MP_\Phi \cap C^{(m)}(\mathbb{R})$ is a solution of the Dunkl equation $P(D_k)u = f$. Then mean-periodic are all the functions $D_k^j u$, $j = 0, 1, 2, \dots, m-1$, i.e.

$$\Phi_y\{T_k^y D_k^j u(x)\} = 0, \tag{37}$$

since the operator $Af(x) = \Phi_y\{T_k^y f(x)\}$ commutes with D_k (Dimovski, Hristov, and Sifi [6]). For $x = 0$ from (37) we get

$$\Phi_y\{T_k^y D_k^j u(0)\} = 0.$$

But $T_k^y D_k^j u(0) = T_k^0 D_k^j u(y)$ ((16), Lemma 6) and hence

$$\Phi\{D_k^j u\} = 0, \quad j = 0, 1, 2, \dots, m-1. \tag{38}$$

In order to prove that a solution u of $P(D_k)u = f$ with $f \in MP_\Phi$, which satisfies conditions (38), is a mean-periodic function, we consider the function

$$v = \Phi_y\{T_k^y u(x)\} = Au.$$

Since the operator A commutes with D_k, then applying it on the equation $P(D_k)u = f$, we get $P(D_k)v = 0$ due to $Af = 0$. It remains to find the initial values $D_k^j v(0)$, $j = 0, 1, 2, \dots, m-1$:

$$D_k^j v(0) = AD_k^j u(0) = \Phi_y\{T_k^y D_k^j u(0)\} = \Phi_y\{T_k^0 D_k^j u(y)\} = \Phi_y\{D_k^j u(y)\} = 0.$$

At the end of the previous section we have seen that the initial value problem $P(D_k)v = 0$, $D_k^j v(0) = 0$, $j = 0, 1, 2, \dots, m-1$, has only the trivial solution $v(x) = 0$. Thus we proved that $\Phi_y\{T_k^y u\} = 0$, i.e. u is mean-periodic. ■

Now we can use operational calculus method for solving nonlocal Cauchy problems for Dunkl equations to find explicitly the mean-periodic solutions of such equations.

To this end, we are to solve the homogeneous nonlocal Cauchy boundary value problem

$$P(D_k)u = f, \quad \Phi\{D_k^j u\} = 0, \ j = 0, 1, 2, \dots, m-1, \tag{39}$$

with $f \in MP_\Phi$.

In the ring $\mathcal{M}_k$ of the multiplier fractions it is reduced to the single algebraic equation for u

$$P(S_k)u = f. \tag{40}$$

As we have seen in Section 5, $P(S_k)$ is a non-divisor of zero in $\mathcal{M}_k$ iff none of the zeros of the polynomial $P(\lambda)$ is a zero of the Dunkl indicatrix $E_k(\lambda)$. If $P(S_k)$ is a divisor of zero, then, in order to ensure the existence of solution of (40) and thus of (39), additional restrictions on f should be imposed. This is the so called *resonance case*, which we will not treat here.

Thus, let $P(S_k)$ be a non-divisor of zero in $\mathcal{M}_k$, i.e. $\{\lambda : P(\lambda) = 0\} \cap \{\lambda : E_k(\lambda) = 0\} = \emptyset$. Then the formal solution of (40) in $\mathcal{M}_k$

$$u = \frac{1}{P(S_k)} f$$

can be written in explicit functional form. Using the extended Heaviside algorithm of Section 6, we represent $\dfrac{1}{P(S_k)}$ as a convolutional operator

$$\frac{1}{P(S_k)} = \{G(x)\} * .$$

Then

$$u = G * f \tag{41}$$

is the desired mean-periodic solution of the Dunkl equation $P(D_k)u = f$. The verification is straightforward. Indeed, $G * f \in MP_\Phi$ according to Theorem 2, since $f \in MP_\Phi$.

Our considerations of the problem for solving Dunkl equations in mean-periodic functions can be summarized in the following

Theorem 10. *A Dunkl equation $P(D_k)u = f$ with $f \in MP_\Phi$ has a unique solution in MP_Φ iff none of the zeros of the polynomial $P(\lambda)$ is a zero of the Dunkl indicatrix*

$$E_k(\lambda) = \Phi\left\{j_{k-\frac{1}{2}}(i\lambda x) + \frac{\lambda x}{2k+1} j_{k+\frac{1}{2}}(i\lambda x)\right\}.$$

In the end, it is possible the Duhamel principle to be extended to the problem for solving Dunkl equations in mean-periodic functions.

Theorem 11. *Let $H(x)$ be the solution of the homogeneous nonlocal Cauchy problem $P(D_k)H = 1$, $\Phi\{D_k^j H\} = 0$, $j = 0, 1, 2, \ldots, m-1$. Then*

$$u = D_k(H * f)$$

is a mean-periodic solution of the Dunkl equation $P(D_k)u = f$ with $f \in MP_\Phi$.

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