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# AERODYNAMIC CHARACTERISTICS OF JOUKOWSKY LIKE WINGS 

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#### Abstract

Aerodynamic characteristics of Joukowsky like airfoils are analyzed, under the assumption that the flow near the airfoil is governed by two-dimensional incompressible isothermal Newtonian fluid flow, beyond the viscous boundarylayer of which is approximated by a potential flow with a new parameter. Vorticity transport equation is solved numerically, using a spectral finite difference scheme to give steady-state various characteristics.


## 1. Introduction

Aerodynamic characteristics of airfoils were investigated experimentally by M. M. Munk [1], E. N. Jacobs [2], E. M. Jacobs \& I. H. Abbott [3], E. A. Jacobs, K. E. Ward, R. M. Pinkerton [4], E. A. Jacobs \& A. Sherman [5], R. H. Neely, T. V. Bollech, G. C. Westrick, R. R. Graham [6], H. C. Garner \& A. S. Baston [7]. At an early stage, under a frictionless incompressible flow assumption, analytical estimation of wing shape effect was presented by M. M. Munk [8], T. Theodorsen [9]. I. H. Abbott \& A. E. Doenhoff published an accumulated book [10]. Also data on aerodynamic characteristics of airfoils were found in Ref. [11].

In this paper analyzed is a flow near the surface of Joukowsky-like airfoil, which is assumed to be two-dimensional and governed by incompressible isothermal Newtonian fluid flow. All the more beyond the viscous boundary-layer the speed of the flow is high so as to be of potential flow, which is uniform far away from the airfoil.

[^0]
## 2. Analysis

### 2.1. Configuration and coordinate system

The space around a Joukowsky-like airfoil is assumed to be given by the dimensionless Cartesian coordinate $(x, y)$ (based on the reference length $L$ ) through a conformal mapping system $(\alpha, \beta)$

$$
\begin{gathered}
x+i y \equiv z=q\left(\zeta^{*}+\frac{c_{1}}{\zeta^{*}}+\frac{c_{2}}{\zeta^{* 2}}\right),\left(q, c_{1}, c_{2}: \text { real constants }\right) \\
\zeta^{*}=\zeta_{0}+\left(1-\zeta_{0}\right) \mathrm{e}^{\alpha+i \beta},\left(\zeta_{0}: \text { complex constant }\left(\left|\zeta_{0}\right| \ll 1\right)\right) \\
\Re\left(\zeta_{0}\right)<0, \Im\left(\zeta_{0}\right) \geq 0, \alpha \geq 0
\end{gathered}
$$

where $\alpha=0$ corresponds to the airfoil surface. The point $\alpha+i \beta=\pi i$ stands for the leading edge, and that $\alpha+i \beta=0$ the trailing edge. The space should be univalent, the sufficient condition of which is

$$
1-c_{1}-2 c_{2}=0,\left|c_{2}\right| \ll 1
$$

which applies hereafter. The constant $q$ is so chosen as

$$
\Re\{z(\alpha=0, \beta=0)-z(\alpha=0, \beta=\pi)\}=1
$$

The inclination of the line from the leading edge to the trailing edge is denoted to be $\psi_{0}$, i.e.

$$
\tan \psi_{0} \equiv \arg (z(\alpha=0, \beta=0)-z(\alpha=0, \beta=\pi))
$$

The chord length $L_{0}$ (the distance between the leading edge and the trailing edge) is given by

$$
L_{0} \cos \psi_{0}=L
$$

### 2.2. Characteristics of configuration

In case of $\left|c_{2}\right|,\left|\zeta_{0}\right| \ll 1$,

$$
\begin{gathered}
q \approx \frac{1}{4}\left(1+c_{2}\right), \\
\psi_{0} \approx \Im\left(\zeta_{0}^{2}-2 c_{2} \zeta_{0}\right) .
\end{gathered}
$$

Profile of the thickness $H$ of the airfoil

$$
x \approx \frac{1}{4}\left\{2 \cos \beta+2 \Re\left(\zeta_{0}\right) \sin ^{2} \beta+c_{2}\left(1-2 \cos \beta+\cos ^{2} \beta\right)\right\}
$$

$$
\begin{gathered}
H \approx\left\{c_{2}-\Re\left(\zeta_{0}\right)\right\} \sin \beta(1-\cos \beta),(0 \leq \beta \leq \pi) \\
H_{\max } \approx \frac{3 \sqrt{3}}{4}\left\{c_{2}-\Re\left(\zeta_{0}\right)\right\} \quad \text { at } \cos \beta=-1 / 2
\end{gathered}
$$

Camber line:

$$
\begin{gathered}
x \approx \frac{\cos \beta}{2} \\
y \approx \frac{1}{2} \Im\left(\zeta_{0}\right) \sin ^{2} \beta .
\end{gathered}
$$

Radius of curvature of the airfoil, $R$, at the leading edge:

$$
R \approx \frac{2\left|\zeta_{0}-c_{2}+2 \zeta_{0}^{2}-4 c_{2} \zeta_{0}\right|^{3}}{\left.\left|\Re\left(\zeta_{0}-c_{2}+2 \zeta_{0}^{2}\right)+2\right| \zeta_{0}\right|^{2}-10 c_{2} \Re\left(\zeta_{0}\right)+4 c_{2}^{2} \mid}
$$

Figure 1 shows an example of a configuration of the airfoils ( $x_{\ell}, y_{\ell}$ : Cartesian coordinate at the leading edge).


Figure 1: Example of configuration $\zeta_{0}=-0.092+0.03 i$
$-: c_{2}=0, R=0.017 ;--: c_{2}=0.02$

### 2.3. Basic equations for the fluid flow

The equation of dimensionless vorticity transport is

$$
\begin{equation*}
J \frac{\partial \zeta}{\partial t}+\frac{\partial(\zeta, \psi)}{\partial(\alpha, \beta)}=\frac{1}{R e}\left(\frac{\partial^{2} \zeta}{\partial \alpha^{2}}+\frac{\partial^{2} \zeta}{\partial \beta^{2}}\right) \tag{1}
\end{equation*}
$$

The relation between vorticity $\zeta$ and a stream function $\psi$ is

$$
\begin{gather*}
J \zeta+\frac{\partial^{2} \psi}{\partial \alpha^{2}}+\frac{\partial^{2} \psi}{\partial \beta^{2}}=0  \tag{2}\\
J \equiv \frac{\partial(x, y)}{\partial(\alpha, \beta)}=\left|\frac{d z}{d(\alpha+i \beta)}\right|^{2},
\end{gather*}
$$

where $R e$ stands for a Reynolds number defined by $R e \equiv \rho U_{\infty} L / \mu$, ( $\rho$ : density of fluid, $\mu$ : viscosity, $U_{\infty}$ : uniform flow speed ).

### 2.4. Boundary conditions

Velocity potential function $f(\alpha+i \beta)$ corresponding to the flow direction $\phi$ is

$$
\begin{gathered}
f(\alpha+i \beta)=q\left|1-\zeta_{0}\right| \times\left[2 \cosh \omega+\left(\frac{1}{1-\epsilon_{2} \cosh 2 \omega}-1\right)+B i(\alpha+i \beta)\right] \\
\omega \equiv \alpha+i \beta+i \beta_{0}-i \phi, \beta_{0} \equiv \arg \left(1-\zeta_{0}\right) ; \epsilon_{2}, B \text { : real. }
\end{gathered}
$$

Potential flow assumption at $\alpha=\alpha_{\infty} \equiv c / \sqrt{R e}, c$ : real positive suitably selected constant (currently $c=5$ ) is given by

$$
\begin{gathered}
\frac{\partial}{\partial \alpha} \psi\left(\alpha=\alpha_{\infty}, \beta\right)=\Im f^{\prime}(i \beta), \\
\zeta\left(\alpha=\alpha_{\infty}, \beta\right)=0
\end{gathered}
$$

A necessary condition is $(\partial / \partial \alpha) \zeta\left(\alpha=\alpha_{\infty}, \beta\right)=0$. No slip conditions on the surface $(\alpha=0)$ gives

$$
\frac{\partial}{\partial \alpha} \psi(0, \beta)=0
$$

and without loss of generality it is assumed

$$
\psi(0, \beta)=0
$$

Continuity of the potential flow at the trailing edge gives

$$
f^{\prime}(0)=0
$$

Also doubly connectedness of the domain through no slip flow gives

$$
\oint_{\alpha=0} \frac{\partial \zeta}{\partial \alpha} d \beta=0
$$

### 2.5. Spectral decomposition

Fourier decomposition applies:

$$
\left[\begin{array}{c}
\psi \\
\zeta
\end{array}\right]=\sum_{n=1}^{\infty}\left[\begin{array}{c}
\psi_{s n}(\alpha, t) \\
\zeta_{s n}(\alpha, t)
\end{array}\right] \sin n \beta+\sum_{n=0}^{\infty}\left[\begin{array}{c}
\psi_{c n}(\alpha, t) \\
\zeta_{c n}(\alpha, t)
\end{array}\right] \cos n \beta
$$

Equations (1)-(2) can be decomposed into each Fourier component.

### 2.6. Discretization in space

In the coordinate $\alpha$, any finite difference approximation with non-uniform grid spacing may apply. Here the following to the $n$-th grid point applies:

$$
\alpha_{n}=h\left(\frac{\sinh (n-1) \gamma}{\sinh \gamma}+1\right)+\alpha_{0}
$$

where $h, \gamma$ : real constants $>0$.

### 2.7. Numerical integration with respect to time

A semi-implicit scheme is applied to get a steady-state solution with a suitably given initial condition.

## 3. Results

### 3.1. Force and moment

The dimensionless force, $\boldsymbol{F}$, acting on the wing (based on $\rho U_{\infty}{ }^{2} L$ ) is

$$
\boldsymbol{F}=\frac{i}{R e}\left\{\oint \frac{d z}{d(\alpha+i \beta)} \zeta d \beta-\oint z \frac{\partial \zeta}{\partial \alpha} d \beta\right\}
$$

The lift coefficient $C_{L}$ is given by the component of $\boldsymbol{F}$, normal to the uniform flow direction, and the drag coefficient $C_{D}$ is given by that parallel to the flow. Attack angle is given by $\phi-\psi_{0}$. The moment relative to the origin of $z, C_{M}$ (based on $\rho U_{\infty}{ }^{2} L^{2}$ ), under a right hand coordinate system is given by

$$
C_{M}=-\frac{1}{2 R e} \oint|z|^{2} \frac{\partial \zeta}{\partial \alpha} d \beta+\frac{1}{2 R e} \oint \zeta \frac{\partial}{\partial \alpha}|z|^{2} d \beta
$$

which is opposite sign to the traditional definition. Traditional lift, drag, moment coefficients are based on $(1 / 2) \rho U_{\infty}{ }^{2} S$ ( $S$ : circumference length), for which

$$
0<(S / 2-L) / L \lesssim 0.05 \text { if }\left|\zeta_{0}\right|,\left|c_{2}\right| \ll 1
$$

Especially if $\zeta_{0}$ is real,

$$
\begin{aligned}
S / L \approx 8(1+\xi) & \sqrt{2 \xi}\left[\frac{\sqrt{\beta^{*}}}{3}\left\{2 \alpha^{*} F(\varphi, k)-\left(\alpha^{*}+\beta^{*}\right) E(\varphi, k)\right\}\right. \\
& \left.+\frac{1+\beta^{*}+2 \alpha^{*}}{3} \sqrt{\frac{1+\beta^{*}}{1+\alpha^{*}}}\right]
\end{aligned}
$$

$$
\begin{gathered}
\beta^{*} \equiv \frac{1}{16 \xi}\left\{1-6 \xi+\sqrt{(1-6 \xi)^{2}-32 \xi^{3}}\right\} \\
\alpha^{*} \equiv \frac{\xi}{8 \beta^{*}}, \varphi=\tan ^{-1}\left(1 / \sqrt{\alpha^{*}}\right), k=\sqrt{\left(\beta^{*}-\alpha^{*}\right) / \beta^{*}} \\
\xi \equiv\left|\zeta_{0}\right|+c_{2}(>0)
\end{gathered}
$$

where $F(\cdot, \cdot), E(\cdot, \cdot)$ : elliptic integral of the first, and of the second kind respectively.

### 3.2. Force characteristics

Figure 2 shows force characteristics against the attack angle.
Figure 3 shows moment characteristics against the attack angle. Present numerical examples shown are for $\epsilon_{2}=-0.1$ unless otherwise stated, e.g. [12].


Figure 2: $\quad \phi-\psi_{0}$ : angle of attack

- : $C_{L}, ~ \Delta: C_{D}: \zeta_{0}=-0.092\left(c_{2}=0\right)$

Figure 3: $\quad \phi-\psi_{0}$ : angle of attack v : $C_{M}: \zeta_{0}=-0.092\left(c_{2}=0, R e=\right.$ ○: $\left.C_{L}, \triangle: C_{D}: \zeta_{0}=-0.092+0.03 i, \quad 10^{6}\right) \nabla: C_{M}: \zeta_{0}=-0.092+0.03 i$ $H_{\text {max }}=0.11, R e=10^{6}, \epsilon_{2}=-0.1 \quad\left(c_{2}=0, R e=10^{6}\right)$

Figure 4 shows the lift dependency on $c_{2}$.
Figure 5 shows comparison of $C_{L}$ vs. angle of attack with experimental ones.


Figure 4: $\phi=0.1 \zeta_{0}=-0.092+0.03 i R e=10^{6}, \epsilon_{2}=-0.1$


Figure 5: Comparison $\circ: \zeta_{0}=-0.092+0.03 i, H_{\max }=0.11 c_{2}=0, R e=10^{6}$
$\bullet: \zeta_{0}=-0.092, c_{2}=0, R e=10^{6} \square: N A C A 0009[4]$ ■ : NACA 2309 [4]

### 3.3. Correlation between lift and drag coefficients

Figure 6 shows correlation between lift and drag coefficients.


Figure 6: Comparison 4: NACA 2309, $R e=1.8 \times 10^{5}$ [4], ○ : $\zeta_{0}=-0.092+$ $0.03 i, c_{2}=0, H_{\max }=0.11, R e=10^{6}, \bullet: \zeta_{0}=-0.092+0.03 i, c_{2}=0, R e=10^{5}$

## 4. Conclusions

Spectral finite difference schemes give good solutions for aerodynamic characteristics of Joukowsky like wings, with configuration characteristics.

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